### INTEGRATED CIRCUITS

# DATA SHEET



# PCA9534

8-bit I<sup>2</sup>C and SMBus, low power I/O port with interrupt

Product data sheet Supersedes data of 2003 Dec 02





### 8-bit I<sup>2</sup>C and SMBus low power I/O port with interrupt

PCA9534



### **FEATURES**

- 8-bit I2C GPIO
- Operating power supply voltage range of 2.3 V to 5.5 V
- 5 V tolerant I/Os
- Polarity inversion register
- Active low interrupt output
- Low stand-by current
- Noise filter on SCL/SDA inputs
- No glitch on power-up
- Internal power-on reset
- 8 I/O pins which default to 8 inputs
- 0 kHz to 400 kHz clock frequency
- ESD protection exceeds 2000 V HBM per JESD22-A114, 200 V MM per JESD22-A115 and 1000 V CDM per JESD22-C101
- Latch-up testing is done to JESDEC Standard JESD78 which exceeds 100 mA
- Offered in three different packages: SO16, TSSOP16, and HVQFN16

#### **DESCRIPTION**

The PCA9534 is a16-pin CMOS device that provide 8 bits of General Purpose parallel Input/Output (GPIO) expansion for  $\rm I^2C/SMBus$  applications and was developed to enhance the Philips family of  $\rm I^2C$  I/O expanders. The improvements include higher drive capability, 5V I/O tolerance, lower supply current, individual I/O configuration, 400 kHz clock frequency, and smaller packaging. I/O expanders provide a simple solution when additional I/O is needed for ACPI power switches, sensors, pushbuttons, LEDs, fans, etc.

The PCA9534 consist of an 8-bit Configuration register (Input or Output selection); 8-bit Input register, 8-bit Output register and an 8-bit Polarity inversion register (Active HIGH or Active LOW operation). The system master can enable the I/Os as either inputs or outputs by writing to the I/O configuration bits. The data for each Input or Output is kept in the corresponding Input or Output register. The polarity of the input port register can be inverted with the Polarity Inversion Register. All registers can be read by the system master. Although pin-to-pin and I<sup>2</sup>C address compatible with the PCF8574 series, software changes are required due to the enhancements and are discussed in *Application Note AN469*.

The PCA9534 is identical to the PCA9554 except for the removal of the internal I/O pull-up resistor which greatly reduces power consumption when the I/Os are held LOW.

The PCA9534 open-drain interrupt output is activated when any input state differs from its corresponding input port register state and is used to indicate to the system master that an input state has changed. The power-on reset sets the registers to their default values and initializes the device state machine.

Three hardware pins (A0, A1, A2) vary the fixed  $I^2C$  address and allow up to eight devices to share the same  $I^2C/SMBus$ .

### ORDERING INFORMATION

PACKAGES	TEMPERATURE RANGE	ORDER CODE	TOPSIDE MARK	DRAWING NUMBER
16-Pin Plastic SO (wide)	−40 °C to +85 °C	PCA9534D	PCA9534D	SOT162-1
16-Pin Plastic TSSOP	−40 °C to +85 °C	PCA9534PW	PCA9534	SOT403-1
16-Pin Plastic HVQFN	–40 °C to +85 °C	PCA9534BS	9534	SOT629-1

Standard packing quantities and other packing data are available at www.standardproducts.philips.com/packaging. I<sup>2</sup>C is a trademark of Philips Semiconductors Corporation.

SMBus as specified by the Smart Battery System Implementers Forum is a derivative of the Philips I<sup>2</sup>C patent.

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### PIN CONFIGURATION — SO, TSSOP

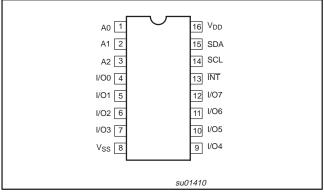


Figure 1. Pin configuration — SO, TSSOP

### PIN CONFIGURATION — HVQFN

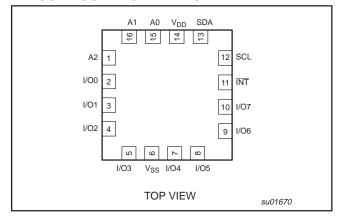


Figure 2. Pin Configuration — HVQFN

### **PIN DESCRIPTION**

PIN NI	JMBER	OVALDO	FUNCTION
SO, TSSOP	HVQFN	SYMBOL	FUNCTION
1	15	A0	Address input 0
2	16	A1	Address input 1
3	1	A2	Address input 2
4–7	2–5	I/O0 to I/O3	I/O0 to I/O3
8	6	V <sub>SS</sub>	Supply ground
9–12	7–10	I/O4 to I/O7	I/O4 to I/O7
13	11	ĪNT	Interrupt output (open drain)
14	12	SCL	Serial clock line
15	13	SDA	Serial data line
16	14	$V_{DD}$	Supply voltage

### **BLOCK DIAGRAM**

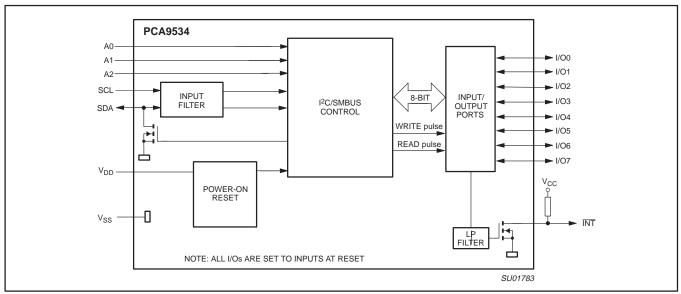


Figure 3. Block diagram

### 8-bit I<sup>2</sup>C and SMBus low power I/O port with interrupt

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# REGISTERS Command Byte

Command	Protocol	Function
0	Read byte	Input port register
1	Read/write byte	Output port register
2	Read/write byte	Polarity inversion register
3	Read/write byte	Configuration register

The command byte is the first byte to follow the address byte during a write transmission. It is used as a pointer to determine which of the following registers will be written or read.

### Register 0 - Input Port Register

bit	17	16	15	14	13	12	l1	10
default	Х	Х	Х	Х	Х	Х	Х	Х

This register is a read only port. It reflects the incoming logic levels of the pins, regardless of whether the pin is defined as an input or an output by Register 3. Writes to this register have no effect.

The default value 'X' is determined by the externally applied logic level.

### Register 1 - Output Port Register

bit	07	O6	O5	04	О3	O2	01	O0
default	1	1	1	1	1	1	1	1

This register reflects the outgoing logic levels of the pins defined as outputs by Register 3. Bit values in this register have no effect on pins defined as inputs. Reads from this register return the value that is in the flip-flop controlling the output selection, NOT the actual pin value.

### Register 2 - Polarity Inversion Register

	bit	N7	N6	N5	N4	N3	N2	N1	N0
Ī	default	0	0	0	0	0	0	0	0

This register allows the user to invert the polarity of the Input Port Register data. If a bit in this register is set (written with '1'), the corresponding Input Port data is inverted. If a bit in this register is cleared (written with a '0'), the Input Port data polarity is retained.

### Register 3 - Configuration Register

bit	C7	C6	C5	C4	C3	C2	C1	C0
default	1	1	1	1	1	1	1	1

This register configures the directions of the I/O pins. If a bit in this register is set, the corresponding port pin is enabled as an input with high impedance output driver. If a bit in this register is cleared, the corresponding port pin is enabled as an output. At reset, the I/Os are configured as inputs.

### **Power-on Reset**

When power is applied to  $V_{DD}$ , an internal power-on reset holds the PCA9534 in a reset condition until  $V_{DD}$  has reached  $V_{POR}$ . At that point, the reset condition is released and the PCA9534 registers and state machine will initialize to their default states. Thereafter,  $V_{DD}$  must be lowered below 0.2 V to reset the device.

For a power reset cycle,  $V_{DD}$  must be lowered below 0.2 V and then restored to the operating voltage.

### **Interrupt Output**

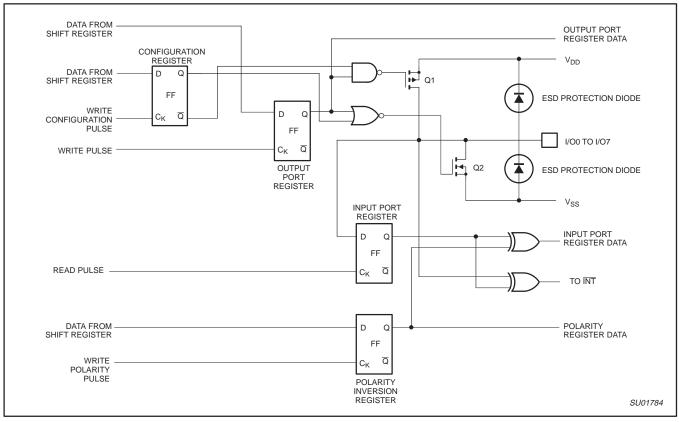
The open-drain interrupt output is activated when one of the port pins change state and the pin is configured as an input. The interrupt is deactivated when the input returns to its previous state or the input port register is read.

Note that changing an I/O from an output to an input may cause a false interrupt to occur if the state of the pin does not match the contents of the input port register.

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### SIMPLIFIED SCHEMATIC OF I/O0 TO I/O7



NOTE: At Power-on Reset, all registers return to default values.

Figure 4. Simplified schematic of I/O0 to I/O7

### I/O port

When an I/O is configured as an input, FETs Q1 and Q2 are off, creating a high impedance input. The input voltage may be raised above  $V_{DD}$  to a maximum of 5.5 V.

If the I/O is configured as an output, then either Q1 or Q2 is enabled, depending on the state of the output port register. Care should be exercised if an external voltage is applied to an I/O configured as an output because of the low impedance paths that exist between the pin and either  $\rm V_{DD}$  or  $\rm V_{SS}$ .

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### **Device address**

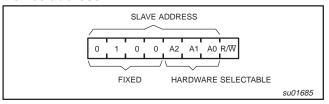


Figure 5. PCA9534 address

### **Bus transactions**

Data is transmitted to the PCA9534 registers using the write mode as shown in Figures 6 and 7. Data is read from the PCA9534 registers using the read mode as shown in Figures 8 and 9. These devices do not implement an auto-increment function so once a command byte has been sent, the register which was addressed will continue to be accessed by reads until a new command byte has been sent.

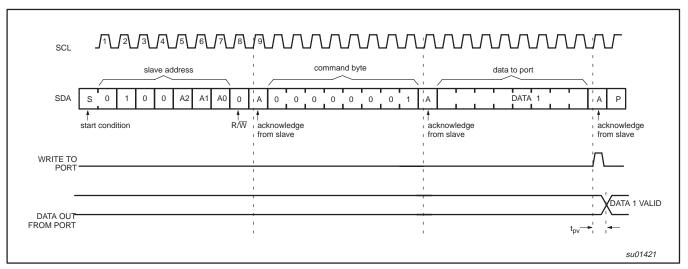


Figure 6. WRITE to output port register

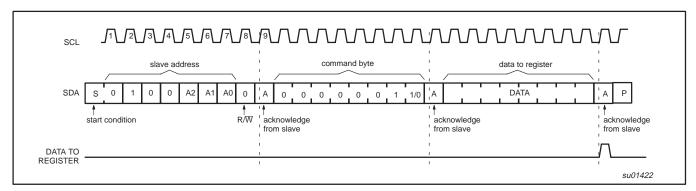


Figure 7. WRITE to configuration or polarity inversion registers

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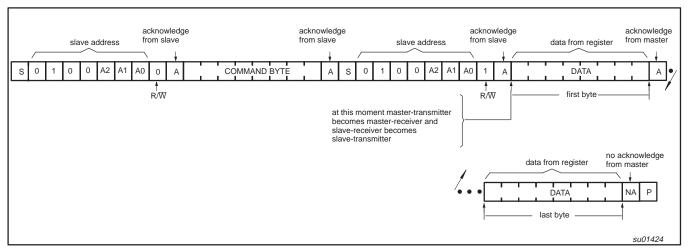
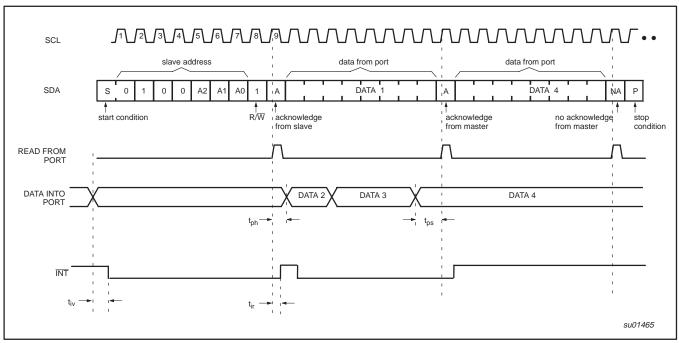


Figure 8. READ from register



#### NOTES

- 1. This figure assumes the command byte has previously been programmed with 00h.
- 2. Transfer of data can be stopped at any moment by a stop condition.

Figure 9. READ input port register

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### TYPICAL APPLICATION

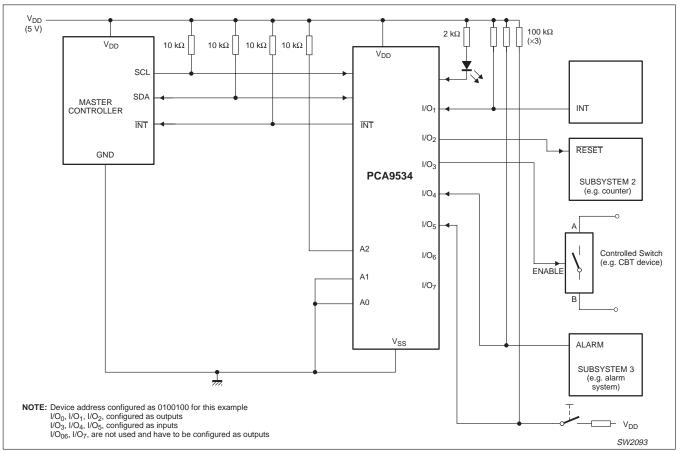


Figure 10. Typical application

### Minimizing I<sub>DD</sub> when the I/O is used to control LEDs

When the I/Os are used to control LEDs, they are normally connected to  $V_{DD}$  through a resistor as shown in Figure 10. Since the LED acts as a diode, when the LED is off the I/O  $V_{IN}$  is about 1.2 V less than  $V_{DD}$ . The supply current,  $I_{DD}$ , increases as  $V_{IN}$  becomes lower than  $V_{DD}$  and is specified as  $\Delta I_{DD}$  in the DC characteristics table.

Designs needing to minimize current consumption, such as battery power applications, should consider maintaining the I/O pins greater than or equal to  $V_{DD}$  when the LED is off. Figure 11 shows a high value resistor in parallel with the LED. Figure 12 shows  $V_{DD}$  less than the LED supply voltage by at least 1.2 V. Both of these methods maintain the I/O  $V_{IN}$  at or above  $V_{DD}$  and prevents additional supply current consumption when the LED is off.

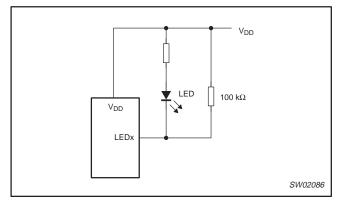


Figure 11. High value resistor in parallel with the LED

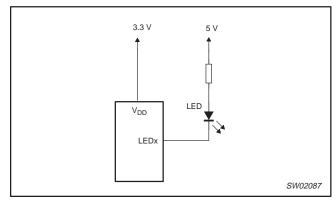


Figure 12. Device supplied by a lower voltage

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### **ABSOLUTE MAXIMUM RATINGS**

In accordance with the Absolute Maximum Rating System (IEC 134)

SYMBOL	PARAMETER	CONDITIONS	MIN	MAX	UNIT
$V_{DD}$	Supply voltage		-0.5	6.0	V
I <sub>I</sub>	DC input current			±20	mA
V <sub>I/O</sub>	DC voltage on an I/O		V <sub>SS</sub> - 0.5	5.5	V
I <sub>I/O</sub>	DC output current on an I/O		_	±50	mA
I <sub>DD</sub>	Supply current			85	mA
I <sub>SS</sub>	Supply current			100	mA
P <sub>tot</sub>	Total power dissipation			200	mW
T <sub>stg</sub>	Storage temperature range		-65	+150	°C
T <sub>amb</sub>	Operating ambient temperature		-40	+85	°C

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### **HANDLING**

Inputs and outputs are protected against electrostatic discharge in normal handling. However, to be totally safe, it is desirable to take precautions appropriate to handling MOS devices. Advice can be found in Data Handbook IC24 under "Handling MOS devices".

### DC CHARACTERISTICS

 $V_{DD}$  = 2.3 V to 5.5 V;  $V_{SS}$  = 0 V;  $T_{amb}$  = -40 °C to +85 °C; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNIT
Supplies		•				
$V_{DD}$	Supply voltage		2.3	_	5.5	V
I <sub>DD</sub>	Supply current	Operating mode; $V_{DD} = 5.5 \text{ V}$ ; no load; $f_{SCL} = 100 \text{ kHz}$	_	104	175	μА
I <sub>stbl</sub>	Standby current	Standby mode; $V_{DD} = 5.5 \text{ V}$ ; no load; $V_{I} = V_{SS}$ ; $f_{SCL} = 0 \text{ kHz}$ ; $I/O = \text{inputs}$	_	0.25	1	μА
I <sub>stbh</sub>	Standby current	Standby mode; $V_{DD} = 5.5 \text{ V}$ ; no load; $V_{I} = V_{DD}$ ; $f_{SCL} = 0 \text{ kHz}$ ; $I/O = \text{inputs}$	_	0.25	1	μА
V <sub>POR</sub>	Power-on reset voltage (Note 1)	No load; V <sub>I</sub> = V <sub>DD</sub> or V <sub>SS</sub>	_	1.5	1.65	V
Input SCL;	input/output SDA	•				
V <sub>IL</sub>	LOW-level input voltage		-0.5	_	0.3V <sub>DD</sub>	V
V <sub>IH</sub>	HIGH-level input voltage		0.7V <sub>DD</sub>	_	5.5	V
I <sub>OL</sub>	LOW-level output current	V <sub>OL</sub> = 0.4 V	3	_	_	mA
ΙL	Leakage current	$V_I = V_{DD} = V_{SS}$	-1	_	+1	μΑ
C <sub>I</sub>	Input capacitance	$V_I = V_{SS}$	_	5	10	pF
I/Os		•			•	•
V <sub>IL</sub>	LOW-level input voltage		-0.5	_	0.8	V
V <sub>IH</sub>	HIGH-level input voltage		2.0	_	5.5	V
		V <sub>OL</sub> = 0.5 V; V <sub>DD</sub> = 2.3 V; Note 2	8	10	_	mA
		V <sub>OL</sub> = 0.7 V; V <sub>DD</sub> = 2.3 V; Note 2	10	13	_	mA
		V <sub>OL</sub> = 0.5 V; V <sub>DD</sub> = 4.5 V; Note 2	8	17	_	mA
I <sub>OL</sub>	LOW-level output current	V <sub>OL</sub> = 0.7 V; V <sub>DD</sub> = 4.5 V; Note 2	10	24	_	mA
		V <sub>OL</sub> = 0.5 V; V <sub>DD</sub> = 3.0 V; Note 2	8	14	_	mA
		V <sub>OL</sub> = 0.7 V; V <sub>DD</sub> = 3.0 V; Note 2	10	19	_	mA
		$I_{OH} = -8 \text{ mA}; V_{DD} = 2.3 \text{ V}; \text{ Note 3}$	1.8	_	_	V
		$I_{OH} = -10 \text{ mA}; V_{DD} = 2.3 \text{ V}; \text{ Note 3}$	1.7	_	_	V
		I <sub>OH</sub> = -8 mA; V <sub>DD</sub> = 3.0 V; Note 3	2.6	_	_	V
V <sub>OH</sub>	HIGH-level output voltage	I <sub>OH</sub> = -10 mA; V <sub>DD</sub> = 3.0 V; Note 3	2.5	_	_	V
		$I_{OH} = -8 \text{ mA}; V_{DD} = 4.5 \text{ V}; \text{ Note 3}$	4.1	_	_	V
		$I_{OH} = -10 \text{ mA}$ ; $V_{DD} = 4.5 \text{ V}$ ; Note 3	4.0	_	_	V
I <sub>IL</sub>	Input leakage current	$V_I = V_{DD} = V_{SS}$	-1	_	1	μΑ
C <sub>I</sub>	Input capacitance		_	5	10	pF
Interrupt IN		•			•	
I <sub>OL</sub>	LOW-level output current	V <sub>OL</sub> = 0.4 V	3	_	_	mA
	ts A0, A1, A2	•				
V <sub>IL</sub>	LOW-level input voltage		-0.5	_	0.8	V
V <sub>IH</sub>	HIGH-level input voltage		2.0	_	5.5	V
ILI	Input leakage current		-1	_	1	μΑ

#### NOTES:

- 1.  $V_{DD}$  must be lowered to 0.2 V in order to reset part.
- 2. Each I/O must be externally limited to a maximum of 25 mA and the device must be limited to a maximum current of 100 mA.

3. The total current sourced by all I/Os must be limited to 85 mA.

# 8-bit I<sup>2</sup>C and SMBus low power I/O port with interrupt

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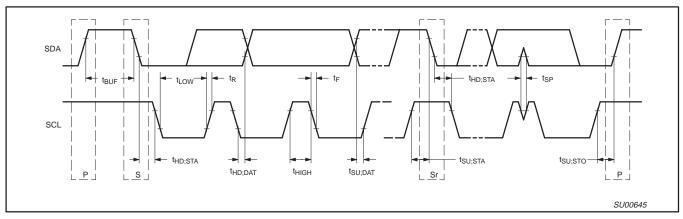


Figure 13. Definition of timing

### **AC SPECIFICATIONS**

SYMBOL	PARAMETER	STANDAF I <sup>2</sup> C-		FAST MO		UNITS
		MIN	MAX	MIN	MAX	
f <sub>SCL</sub>	Operating frequency	0	100	0	400	kHz
t <sub>BUF</sub>	Bus free time between STOP and START conditions	4.7	_	1.3	_	μs
t <sub>HD;STA</sub>	Hold time after (repeated) START condition	4.0	_	0.6	_	μs
t <sub>SU;STA</sub>	Repeated START condition setup time	4.7	_	0.6	_	μs
t <sub>SU;STO</sub>	Setup time for STOP condition	4.0	_	0.6	_	μs
t <sub>HD;DAT</sub>	Data in hold time	0	_	0	_	ns
t <sub>VD;ACK</sub>	Valid time for ACK condition <sup>2</sup>	0.3	3.45	0.1	0.9	μs
t <sub>VD;DAT</sub>	Data out valid time <sup>3</sup>	300	_	50	_	ns
tsu;dat	Data setup time	250	_	100	_	ns
t <sub>LOW</sub>	Clock LOW period	4.7	_	1.3	_	μs
tHIGH	Clock HIGH period	4.0	_	0.6	_	μs
t <sub>F</sub>	Clock/Data fall time	_	300	20 + 0.1 C <sub>b</sub> <sup>1</sup>	300	ns
t <sub>R</sub>	Clock/Data rise time	_	1000	20 + 0.1 C <sub>b</sub> <sup>1</sup>	300	ns
t <sub>SP</sub>	Pulse width of spikes that must be suppressed by the input filters	_	50	_	50	ns
Port Timing						
t <sub>PV</sub>	Output data valid		200	_	200	ns
t <sub>PS</sub>	Input data setup time	100	_	100	_	ns
t <sub>PH</sub>	Input data hold time	1	_	1	_	μs
Interrupt Timi	ng					
t <sub>IV</sub>	Interrupt valid	_	4		4	μs
t <sub>IR</sub>	Interrupt reset	_	4		4	μs

- C<sub>b</sub> = total capacitance of one bus line in pF.
   t<sub>VD;ACK</sub> = time for Acknowledgement signal from SCL LOW to SDA (out) LOW.
   t<sub>VD;DAT</sub> = minimum time for SDA data out to be valid following SCL LOW.

# 8-bit I<sup>2</sup>C and SMBus low power I/O port with interrupt

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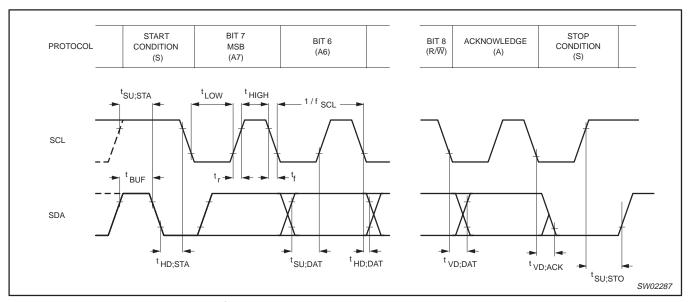


Figure 14. I<sup>2</sup>C-bus timing diagram; rise and fall times refer to V<sub>IL</sub> and V<sub>IH</sub>

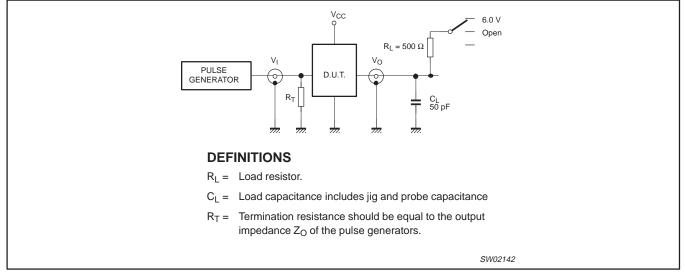


Figure 15. Test circuitry for switching times

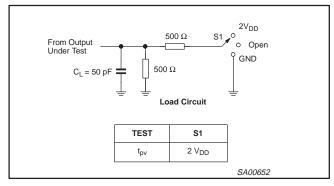


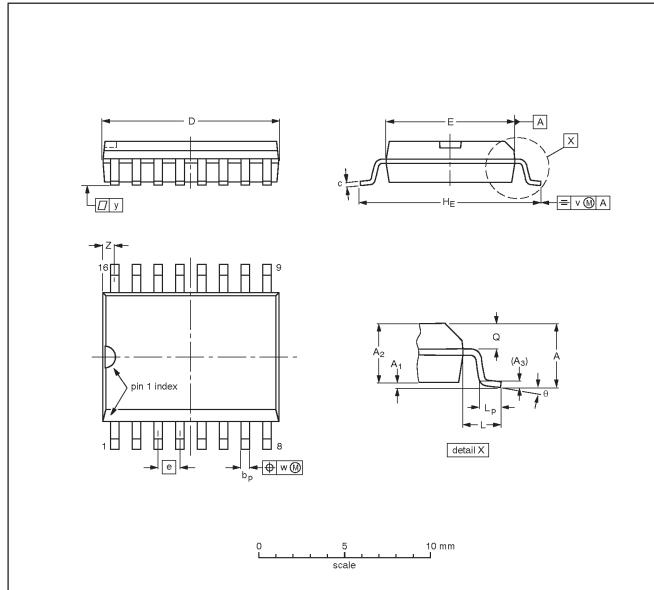
Figure 16. Test circuit

# 8-bit I<sup>2</sup>C and SMBus low power I/O port with interrupt

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### SO16: plastic small outline package; 16 leads; body width 7.5 mm

SOT162-1



### DIMENSIONS (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	bp	c	D <sup>(1)</sup>	E <sup>(1)</sup>	e	HE	L	Lp	Q	٧	w	у	z <sup>(1)</sup>	θ
mm	2.65	0.3 0.1	2.45 2.25	0.25	0.49 0.36	0.32 0.23	10.5 10.1	7.6 7.4	1.27	10.65 10.00	1.4	1.1 0.4	1.1 1.0	0.25	0.25	0.1	0.9 0.4	8°
inches	0.1	0.012 0.004	0.096 0.089	0.01	0.019 0.014	0.013 0.009	0.41 0.40	0.30 0.29	0.05	0.419 0.394	0.055	0.043 0.016	0.043 0.039	0.01	0.01	0.004	0.035 0.016	0°

#### Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

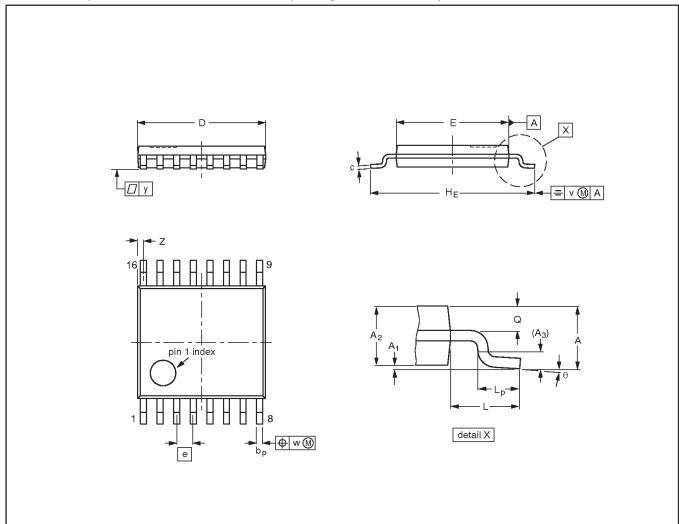
OUTLINE		REFER	EUROPEAN	ISSUE DATE		
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
SOT162-1	075E03	MS-013				<del>99-12-27</del> 03-02-19

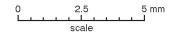
# 8-bit I<sup>2</sup>C and SMBus low power I/O port with interrupt

PCA9534

TSSOP16: plastic thin shrink small outline package; 16 leads; body width 4.4 mm

SOT403-1





### DIMENSIONS (mm are the original dimensions)

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	bp	С	D <sup>(1)</sup>	E <sup>(2)</sup>	е	HE	L	Lp	Q	v	w	у	Z <sup>(1)</sup>	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	5.1 4.9	4.5 4.3	0.65	6.6 6.2	1	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.40 0.06	8° 0°

#### Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

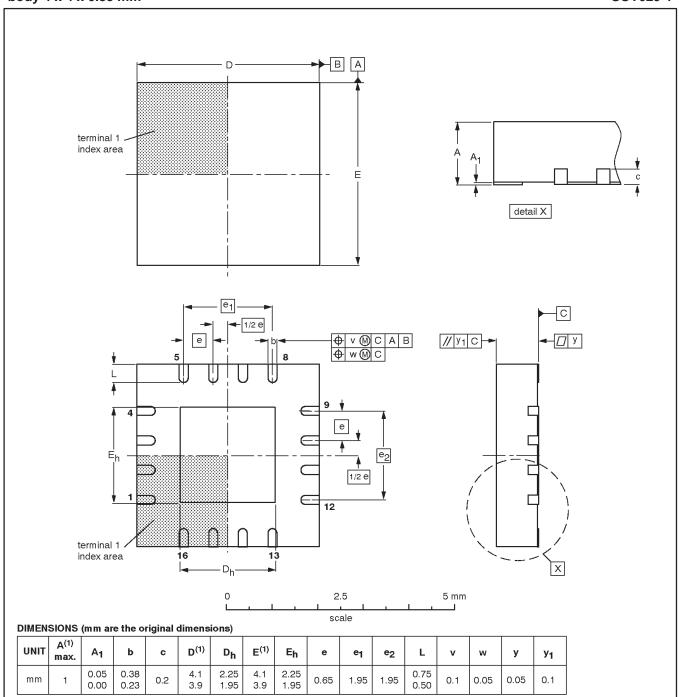
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SOT403-1		MO-153				<del>-99-12-27-</del> 03-02-18	

### 8-bit I<sup>2</sup>C and SMBus low power I/O port with interrupt

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HVQFN16: plastic thermal enhanced very thin quad flat package; no leads; 16 terminals; body  $4 \times 4 \times 0.85$  mm

SOT629-1



### Note

1. Plastic or metal protrusions of 0.075 mm maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE			
VERSION	IEC	JEDEC	JEITA		PROJECTION	1330E DATE	
SOT629-1		MO-220				<del>-01-08-08-</del> 02-10-22	

# 8-bit I<sup>2</sup>C and SMBus low power I/O port with interrupt

PCA9534

### **REVISION HISTORY**

Rev	Date	Description
_2	20040930	Product data sheet (9397 750 13506); Supersedes data of 02 December 2003 (9397 750 12454).
		Modifications:
		● "Register 0—Input Port Register" section on page 4: add second paragraph.
		Section "Power-on reset" on page 4 re-written.
		● Figure 10: resistor values modified
		(New) Note 1 added to DC Characteristics table on page 10.
		"DC Characteristics" table: Note 2 re-written.
_1	20031202	Product data (9397 750 12454); ECN 853-2319 01-A14517 dated 14 November 2003.

### 8-bit I<sup>2</sup>C and SMBus low power I/O port with interrupt

PCA9534



Purchase of Philips I<sup>2</sup>C components conveys a license under the Philips' I<sup>2</sup>C patent to use the components in the I2C system provided the system conforms to the I<sup>2</sup>C specifications defined by Philips. This specification can be ordered using the code 9398 393 40011.

#### Data sheet status

Level	Data sheet status [1]	Product status <sup>[2]</sup> [3]	Definitions
I	Objective data	Development	This data sheet contains data from the objective specification for product development.  Phillips Semiconductors reserves the right to change the specification in any manner without notice.
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<sup>[1]</sup> Please consult the most recently issued data sheet before initiating or completing a design.

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Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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#### Contact information

For additional information please visit

Fax: +31 40 27 24825 http://www.semiconductors.philips.com.

For sales offices addresses send e-mail to:

sales.addresses@www.semiconductors.philips.com

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<sup>[2]</sup> The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.

<sup>[3]</sup> For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.