



IQS221 Datasheet IQ Switch® - ProxSense® Series

9-Channel Capacitive Touch Sensor with Proximity Detection

The IQS221 ProxSense[®] IC is a fully integrated multi-channel capacitive sensor. The IC can be operated as a stand-alone device or interfaced with a microprocessor. Additionally it features an internal system regulator, ensuring class leading proximity sensitivity, stability and unparalleled cost.

Through unique patented technology a solution is offered to replace conventional electromechanical switches in a cost effective manner. ProxSense[®] is capable of detecting a differentiated physical contact (Touch) or Proximity condition through almost any dielectric, allowing the designer to project touch pads or sliders through a variety of materials.

RoHS **Main Features** compliant Multiple channel touch sensor Direct or Coded or serial data output ☐ Used in Slide switches and Keypads Representation □ Automatic Environment Compensation only, not actual On-Chip Integrated Series regulator marking On-Chip Digital Signal Processing ☐ Synchronises to AC supply voltage (or external synchronisation source) ☐ User selectable Proximity and Physical Contact(Touch) sensitivity settings ☐ Low Power Mode suitable for battery applications (27uA) □ Suitable for various dielectrics overlays □ Detect Touch through up to 7mm overlay □ Active driven shield pin OTP options Development and Programming tools available (VisualProxSense and USBPRog) □ QFN5x5-32 / SO-32 packages offered **Applications** Consumer electronics **Human Interface Devices** ☐ GSM cellular telephones / PDA's □ Wake-up from standby applications White goods and appliances ☐ GUI trigger on proximity detection (Azoteq Patent) ☐ Keypads / any electromechanical switches POS terminals ☐ Flame proof, hazardous environment

Available options

| T _A | SO-32 & QFN5x5-32 |
|----------------|-------------------|
| 0°C to 70°C | IQS221 |





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1 Overview

Actuation with built-in intelligence is now possible through touch or mere proximity to a sense pad. The IQS221 enables easy integration of a multiple channel proximity sensor.

The IQS221 can be operated in standalone applications in the Direct and Coded Modes. The IQS221 also offers 2 Serial Modes in which the IQS221 can communicate with a Master Module. The device uses the industry standard SPI Protocol when used in the Serial output mode.

The IQS221 is designed to operate from a DC supply voltage, but can be synchronised to an AC supply voltage, enabling improved proximity sensitivity. An integrated series regulator eliminates the need for expensive external regulators. Current consumption is low enough for battery powered devices. (27uA in LP4)

Value is added through a variety of sensitivity settings, automatic or fixed low power operation, user selectable sensitivity settings and control over the environmental compensation.

1.1 Applicability

All specifications, except where specifically mentioned otherwise, provided by this datasheet are applicable to the following ranges:

| Τ | em | per | ratu | re (| C | to | +7 | 0 | C |
|---|----|-----|------|------|---|----|----|---|---|
| | | | | | | | | | |

2 Analogue Functionality

The analogue circuitry measures the capacitance of a sense electrode attached to the Cx pin through a charge transfer process that is periodically initiated by the digital circuitry. The measuring process is referred to as a conversion and consists of the discharging of Cs and Cx, the charging of Cx and then a series of charge transfers from Cx to Cs until a trip voltage is reached. The number of charge transfers required to reach the trip voltage is referred to as the count (CS).

The capacitance measurement circuitry makes use of the external Cs capacitor and should be chosen for every specific application (recommended sizes given in datasheet).

The IQS221 deploys circuitry to drive a shield that will follow the voltage sensed on Cx (dependent onto which Cx SHLDIN is connected).

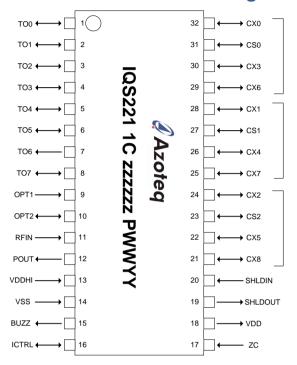
The IQS221 further also deploys advanced RF immunity and a RF detection circuit capable of detecting the presence of RF signals that may influence CS. The circuitry notifies the digital circuitry when RF has been detected.

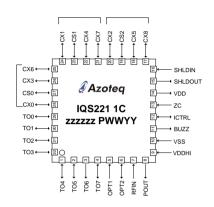
[☐] Supply voltage (V_{DDHI}) 3.0V to 5.0V



3 Device Details

3.1 SO-32 & QFN32-5x5 Packages





SO-32 Package

QFN5x5-32 Package





3.2 Pin-out SO-32

| Pin | Name | Function | I/O | POR ¹ Option | Description |
|-----|-----------|----------|--------------------|-------------------------|---|
| 1 | TO0 | TO0 | Bi-directional | CX[0:7] Touch0 | Physical contact Output 0 |
| 2 | TO1 / | TO1 | Output | CX[0:7] | Physical contact Output 1 |
| | MOSI | MOSI | Input | Touch1 | Data output from master |
| | TO2/ | TO2 | Output | CX8 Touch0 | Physical contact Output 2 |
| 3 | SOMI | SOMI | Output | CX8 Touchu | Data output from slave |
| | | TO3 | Bi-directional | | Physical contact Output 3 |
| 4 | TO3 / RDY | RDY | Output | | Data available indication from slave |
| 5 | TO4 / SCK | TO4 | Bi-directional | CX8 Touch1 | Physical contact Output 4 |
| 5 | 104/3CK | SCK | Input | CAO TOUCHT | Clock from Master |
| 6 | TO5 / /SS | TO5 | Bi-directional | CV[0:7] Drov | Physical contact Output 5 |
| 6 | 1057755 | /SS | Input | CX[0:7] Prox | Not Slave select, active low |
| 7 | TO6 | TO6 | Output | CX8 Prox0 | Physical contact Output 6 |
| 8 | TO7 | TO7 | Bi-directional | CX8 Prox1 | Physical contact Output 7 |
| 9 | OPT1 | OPT1 | Input | - | Dynamic LP / NP Dynamic Switching |
| 10 | OPT2 | OPT2 | Bi-directional | ı | Dynamic Halt Charge, Ready |
| 11 | RFIN | RF Input | Input | - | RF antenna input for RF detection |
| 12 | POUT | POUT | Output | - | Proximity Output |
| 13 | VDDHI | VDDHI | Supply Input | - | Supply Voltage Input |
| 14 | VSS | VSS | Ground Input | - | GND Reference |
| 15 | Buzz | BUZZ | Output | - | Buzzer Output |
| 16 | ICTRL | ICTRL | Custom | ı | Current Reference |
| 17 | ZC | ZC | Analogue Input | - | Zero Cross AC input |
| 18 | VDD | VDD | Analogue Output | - | Internal Regulator Pin (Connect 1uF Capacitor to VSS) |
| 19 | SHLDOUT | SHLDOUT | Output | - | Shield Output |
| 20 | SHLDIN | SHLDIN | Bi-directional | - | Shield Input |
| 21 | CX8 | CX8 | Bi-directional | - | Sense Electrode 8 |
| 22 | CX5 | CX5 | Bi-directional | - | Sense Electrode 5 |
| 23 | CS2 | CS2 | Bi-directional | - | Reference Capacitor 2 |
| 24 | CX2 | CX2 | Bi-directional | - | Sense Electrode 2 |
| 25 | CX7 | CX7 | Bi-directional | - | Sense Electrode 7 |
| 26 | CX4 | CX4 | Bi-directional | - | Sense Electrode 4 |
| 27 | CS1 | CS1 | Bi-directional | - | Reference Capacitor 1 |
| 28 | CX1 | CX1 | Bi-directional | - | Sense Electrode 1 |
| 29 | CX6 | CX6 | Bi-directional | - | Sense Electrode 6 |
| 30 | CX3 | CX3 | Bi-directional | - | Sense Electrode 3 |
| 31 | CS0 | CS0 | Bi-directional | - | Reference Capacitor 0 |
| 32 | CX0 | CX0 | Bi-directional | - | Sense Electrode 0 |

¹ POR = Power On Reset. POR options are used to determine Prox/Touch sensitivity with start-up





3.3 Pin-out QFN32-5x5

| Pin | Name | Function | I/O | POR ² Option | Description |
|-----|---------------|----------|--------------------|-------------------------|---|
| 1 | TO 4 / COK | TO4 | Bi-directional | CV0 Tayloh 1 | Physical contact Output 4 |
| | TO4 / SCK | SCK | Input | CX8 Touch1 | Clock from Master |
| 2 | TOF //CC | TO5 | Bi-directional | CV[0.7] Drov | Physical contact Output 5 |
| | TO5 / /SS | /SS | Input | CX[0:7] Prox | Not Slave select, active low |
| 3 | TO6 | TO6 | Output | CX8 Prox0 | Physical contact Output 6 |
| 4 | TO7 | TO7 | Bi-directional | CX8 Prox1 | Physical contact Output 7 |
| 5 | OPT1 | OPT1 | Input | - | Dynamic LP / NP Dynamic Switching |
| 6 | OPT2 | OPT2 | Bi-directional | - | Dynamic Halt Charge, Ready |
| 7 | RFIN | RF Input | Input | - | RF antenna input for RF detection |
| 8 | POUT | POUT | Output | ı | Proximity Output |
| 9 | VDDHI | VDDHI | Supply Input | - | Supply Voltage Input |
| 10 | VSS | VSS | Ground Input | - | GND Reference |
| 11 | Buzz | BUZZ | Output | - | Buzzer Output |
| 12 | ICTRL | ICTRL | Custom | ı | Current Reference |
| 13 | ZC | ZC | Analogue Input | ı | Zero Cross AC input |
| 14 | VDD | VDD | Analogue Output | - | Internal Regulator Pin (Connect 1uF Capacitor to VSS) |
| 15 | SHLDOUT | SHLDOUT | Output | - | Shield Output |
| 16 | SHLDIN | SHLDIN | Bi-directional | - | Shield Input |
| 17 | CX8 | CX8 | Bi-directional | - | Sense Electrode 8 |
| 18 | CX5 | CX5 | Bi-directional | - | Sense Electrode 5 |
| 19 | CS2 | CS2 | Bi-directional | - | Reference Capacitor 2 |
| 20 | CX2 | CX2 | Bi-directional | - | Sense Electrode 2 |
| 21 | CX7 | CX7 | Bi-directional | - | Sense Electrode 7 |
| 22 | CX4 | CX4 | Bi-directional | - | Sense Electrode 4 |
| 23 | CS1 | CS1 | Bi-directional | - | Reference Capacitor 1 |
| 24 | CX1 | CX1 | Bi-directional | - | Sense Electrode 1 |
| 25 | CX6 | CX6 | Bi-directional | - | Sense Electrode 6 |
| 26 | CX3 | CX3 | Bi-directional | - | Sense Electrode 3 |
| 27 | CS0 | CS0 | Bi-directional | - | Reference Capacitor 0 |
| 28 | CX0 | CX0 | Bi-directional | - | Sense Electrode 0 |
| 29 | TO0 | TO0 | Bi-directional | CX[0:7] Touch0 | Physical contact Output 0 |
| 30 | TO1 / MOSI | TO1 | Output | CX[0:7] Touch1 | Physical contact Output 1 |
| | | MOSI | Input | - | Data output from master |
| 31 | TO2/ | TO2 | Output | CX8 Touch0 | Physical contact Output 2 |
| 01 | SOMI | SOMI | Output | - | Data output from slave |
| | | TO3 | Bi-directional | - | Physical contact Output 3 |
| 32 | TO3 / RDY | RDY | Output | - | Data available indication from slave |

² POR = Power On Reset. POR options are used to determine Prox/Touch sensitivity with start-up



3.4 Schematic

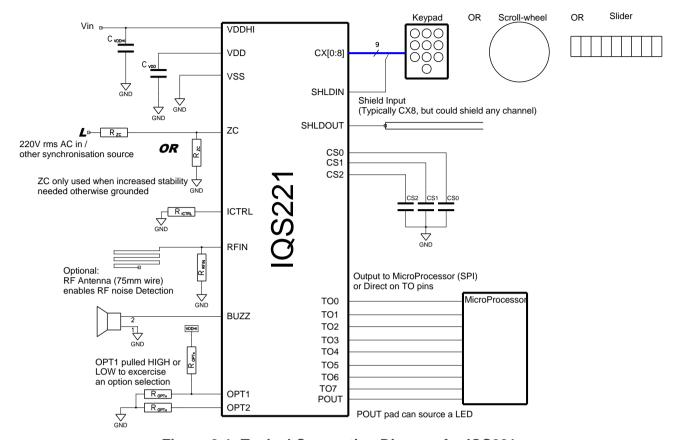


Figure 3-1: Typical Connection Diagram for IQS221

3.4.1 Typical Values

| Component | Value | Comment | | | | | |
|--------------------|----------------------------------|--|--------------|--------------------------|---------------------------|--|--|
| Cs[2:0] | 33nF | Range: 10nF – 100nF. Higher value will have increased sensitivity but decreased response time. | | | | | |
| R _{ICTRL} | 43k Ω | IC current reference | | | | | |
| R _{CX} | 2kΩ | Resistor between CX pad and touch pad. Res | istor incr | eases ESD i | mmunity | | |
| V_{DD} | 1uF | Adding a 100pF capacitor in parallel will increa | ase EMC | (RF) immun | ity | | |
| V_{DDHI} | 1uF | Adding a 100pF capacitor in parallel will increa | ase EMC | (RF) immun | ity | | |
| | | R _{OPTx} used as static selection or dynamically: | | HIGH | LOW | | |
| R _{OPTx} | 100kΩ | | OPT1 OPT2 | NP Halt Charge Transfers | LP Normal Operation | | |
| R _{TOx} | 100kΩ | Used for sensitivity selection on TO pins (alter value written in through SPI) | natively | | | | |
| R _{RFIN} | 50Ω | RF matching impedance | | | | | |
| | 100k Ω to GND | IC not synchronised to external source OR | | | | | |
| R _{ZC} | R _{ZC} to synch. source | Synchronised to external source with maximum amplitude V_{ZC} (i.e. if synchronized to 230V AC, 3 x 20k Ω (125mW) resistors) | | | | | |
| R _{SHLD} | 100kΩ | RSHLD (SHLDOUT to VDDHI) increases shielding, only required if shield is used. Smaller resistor will give better shielding but increased current consumption | | | | | |





Detailed Description

4 Configuration Options

The IQS221 provides One Time Programmable (OTP) user options (each option can be modified only once). The device is fully functional in the default (unconfigured) state. OTP options are intended for specific applications.

The configuration of the device can be done on packaged devices or in-circuit. In-circuit configuration may be limited by values of external components chosen.

Azoteq can supply pre-configured devices for large quantities.

4.1 Device Configuration

Azoteq offers a Configuration Tool (CTxxx) and accompanying software (USBProg.exe) that can be used to program the OTP user options for prototyping purposes. More details regarding the configuration of the device with the USBProg program is explained by application note: "AZD007 – USBProg Overview" which can be found on the Azoteq website.

Alternate programming solutions of the IQS221 also exist. For further enquiries regarding this matter please contact Azoteq at ProxSenseSupport@azoteq.com or the local distributor

Table 4-1: User Selectable Configuration Options: Bank 0

| TO5 | TO2 | TO1 | TO0 | OUTPUT3 | OUTPUT2 | OUTPUT1 | OUTPUT0 |
|---------|---|---|--|--|---------|-------------|---------|
| bit 7 | 1 | | I | 1 | • | | bit 0 |
| | | | | | | | |
| bit 0-3 | 000 000 001 001 010 011 011 100 100 101 110 110 | 0 = DIR-A: 1 = DIR-B: 0 = DIR-F: 1 = DIR-C: 0 = DIR-E: 1 = DIR-G: 0 = CODEI 1 = DIR-D: 0 = CODEI 1 = CODEI 1 = CODEI 0 = NOT U 1 = SPI-L: | Direct Mod Direct Mod Toggle Mo Minimum I Minimum I Current M. D-J: Curren Minimum I D-I: Minimu D-H: Minimu D-H: Minimu SED Normalized Raw value SED SED | le (all channels) de Mode (Cx8 independe Mode (Toggle) ode it Mode Mode (all channels) im Mode (all channels um Mode (Cx8 indepe | ent) | Section 6.1 | |
| bit 4-5 | | | | | | | |
| bit 6 | TO2: TO pin state control -Section 6.3 | | | | | | |
| bit 7 | Channel 8 Touch sensitivity selection (with external TO4) TO5: TO pin state control -Section 6.3 Channel 7 Proximity sensitivity selection | | | | | | |





Table 4-2: User Selectable Configuration Options: Bank 1

| FASTCHA | RGE | LP1 | LP0 | XLP | EXT/INT_SEN | PROXLVLSEL | TO7 | TO6 |
|-----------|----------|------------|--------------|---------------|----------------------------|---------------------|-----|-------|
| bit 15 | | | | | | | | bit 8 |
| | | | | | | | | |
| bit 8-9 | | | s' state co | ntrol | | -Section 6.3 | | |
| | See Ta | | | | | | | |
| bit 10 | | | roximity L | evel select | ion | -Section 6.3 | | |
| | 0 = Def | | | | | | | |
| bit 11 | | ernative | nut conciti | with through | h External / Internal cala | ctions -Section 6.3 | | |
| DILTI | 0 = Ext | | iput sensiti | vity triloug | h External / Internal sele | ctions -Section 6.5 | | |
| | 1 = Inte | | | | | | | |
| bit 12 | | | ow power | Mode enal | ole/disable control bit | -Section 6.4 | | |
| | | ble XLP | • | | | | | |
| | 1 = disa | able XLP | | | | | | |
| bit 13-14 | | | wer mode | select (onl | y used if OPT1 = LOW) | -Section 6.5 | | |
| | 00 = LF | = | | | | | | |
| | 01 = LF | _ | | | | | | |
| | 10 = LF | - | | | | | | |
| | 11 = LF | 94 | | | | | | |
| bit 15 | | | | | isable control bit | -Section 6.6 | | |
| | | | | AMPLE = | | | | |
| | 1 = ena | ble Fast c | harge (TS/ | $AMPLE = \pm$ | ±15ms) | | | |

Table 4-3: User Selectable Configuration Options: Bank 2

| | ND | ND - CONVDIV SHIELD ZOOM HALT | | HALT1 | HALT0 | | |
|--------|----------------|---|----------------------|---------------------------------|-------|--------------|--------|
| bit 23 | | - | | | | | bit 16 |
| | | | | | | | |
| bit 16 | | | | ne-out (T_{HALT}) control bit | S | -Section 6.7 | |
| | | 00 = 20 s | | | | | |
| | - | 01 = 40 s 10 = Neve | | | | | |
| | | 10 = 14eV6 11 = Alwa | | | | | |
| bit 18 | | | oom enable/disable | e control bit | | -Section 6.8 | |
| | C |) = Disab | le Zoom | | | | |
| | - | = Enabl | | | | | |
| bit 19 | | SHIELD:) = Enabl | Shield enable/disal | ole control bit | | -Section 8 | |
| | - |) = ⊑nabi = Disab | | | | | |
| bit 20 | | | : Set the conversion | on frequency | | -Section 6.9 | |
| | | | Hz (nominal) | , , | | | |
| | | 1 = 125kHz (nominal) | | | | | |
| bit 21 | | -: Not used | | | | | |
| bit 22 | - | ND: Noise detect enable/disable control bit -Section 9.2 0 = Enable ND | | | | | |
| | 1 = Disable ND | | | | | | |
| bit 21 | | : Not use | | | | | |



5 Measuring capacitance using the 'Charge Transfer' method

The charge transfer method of capacitive sensing is employed on the IQS221. (The Charge Cycle principle is thoroughly described in APP NOTE "AZD0004: Azoteq Capacitive Sensing".)

A charge cycle is used to take a measurement of the capacitance of a sense electrode (connected to CXx) relative to ground. It consists of a series of pulses charging Cx and discharging Cx to the reference capacitor, at the charge transfer frequency (F_{CX} - refer to Section 6.9). The count of the pulses required to reach a trip voltage on the reference capacitor is referred to as a count (CS) which is the instantaneous capacitive measurement. The CS is used determine if either a physical contact or proximity event occurred (see Section 6.7 for more details on how a proximity and physical contact events are determined and differentiated between).

Three CX channels are multiplexed into one CS reference capacitor as indicated in Table 5-1 and **Figure 5-1**. The Charge Cycles of the IQS221 can be measured on the CS Pins.

From Table 5-1, the designer should determine which CS capacitors to place, depending on the number of CX channels employed.

Typical size of CS capacitor is 33nF, but it can range from 10nF (less sensitive) to 100nF (very sensitive / almost unstable), depending on the layout. If more ground planes or foreign traces exist close to the

CX lines, it is advisable to have a bigger CS capacitor.

Example: A 5 channel application will utilise CX[0, 1, 3, 4, 6] for the Touch pads and CS0 and CS1. Unused CX channels are grounded.

For applications requiring Proximity sensing, it is proposed to utilise CX8 and CS2, as CX8 has an individual threshold setting for improved Proximity sensitivity. A large copper pour will serve as a good Proximity electrode.

Table 5-1- Multiplexed charging scheme

| | cs | | |
|---------|---------|---------|-----|
| Group A | Group B | Group C | CS |
| CX0 | CX3 | CX6 | CS0 |
| CX1 | CX4 | CX7 | CS1 |
| CX2 | CX5 | CX8 | CS2 |

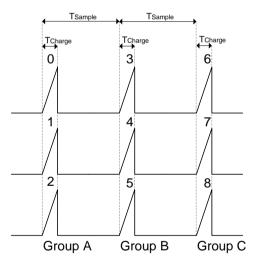


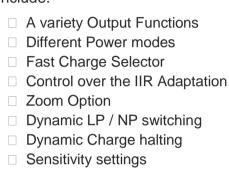
Figure 5-1- Multiplexed charging scheme

Please Note: If using the IQS221 capacitive sensor in an application which may have a wide operating temperature ($\Delta \geq 30^{\circ}$ C) it is recommended to use COG capacitors to maintain the same sensitivity throughout.



6 Descriptions of User Functions

The IQS221 IC can be configured to act as a multi-channel physical contact (/touch) sensor, while all the channels can sense proximity. The IC can be fully customised for almost any design by using a combination of internal programmable functions and external chosen options through resistors. The User Options include.



6.1 Output Function

The output mode is programmed by setting the required configuration bits. A number of output configurations are available on the IQS221. The possible output configurations of the IQS221 fall in three categories, which include Direct, Binary Coded or interfaced with a microprocessor (SPI).

For all Direct and Binary Coded User Interfaces (UI's): Upon the detection of a proximity on any of the pins, the POUT pin will go HIGH for as long as the proximity condition occurs.

The POUT pin is active high, and can source I_{POUT}, enough to drive a LED.

All output pins are sourced from VDDHI when active. The Buzzer is enabled except if stated otherwise.

Table 6-1- User selectable Output modes

| UI # Output pin Function | | | | | | |
|--|--------------------------------|--|--|--|--|--|
| | Direct Mode | | | | | |
| DIR-A | Direct Mode | | | | | |
| DIR-B | Direct Mode (all channels) | | | | | |
| DIR-C | Minimum Mode (CX8 independent) | | | | | |
| DIR-D | Minimum Mode (all channels) | | | | | |
| DIR-E | Minimum Mode (Toggle) | | | | | |
| DIR-F | Toggle Mode | | | | | |
| DIR-G | Current Mode | | | | | |
| | Binary Coded Mode | | | | | |
| Coded - H | Minimum Mode (CX8 independent) | | | | | |
| Coded - H | Minimum Mode (all channels) | | | | | |
| Coded - H | Current Mode | | | | | |
| Serial Peripheral Interface (SPI) Mode | | | | | | |
| SPI-L | Normalized values | | | | | |
| SPI-M | Counts (raw) | | | | | |

Direct Modes

6.1.1 DIR-A Direct Mode

DIR-A gives an Active HIGH output on pins TO[0,1,2,3,4,5,6,7] if a touch is detected on the corresponding sensing pins CX[0,1,2,3,4,5,6,8].

(Note: CX7 is not used in this configuration)

Table 6-2- DIR-A

| Pin State | Input Pins | Output Pins |
|-----------|-------------|-------------|
| Active | CX[0,1,2,3, | TO[0,1,2,3, |
| HIGH | 4,5,6,8] | 4,5,6,7] |

6.1.2 DIR-B Direct Mode (all channels)

DIR-B gives an Active HIGH output on pins TO[0,1,2,3,4,5,6,7], BUZZ if a touch is detected on the corresponding sensing pins CX[0,1,2,3,4,5,6,7,8].

Table 6-3- DIR-B

| Pin State | Input Pins | Output Pins |
|-----------|-------------|----------------|
| Active | CX[0,1,2,3, | TO[0,1,2,3, |
| HIGH | 4,5,6,7,8] | 4,5,6,7], BUZZ |

^{*}No buzzer functionality, only logical output



6.1.3 DIR-C Minimum Mode (Cx8 independent)

The touch creating the biggest change in capacitance, or in other words pressed with the largest part of the finger will register as the current touch. Only one touch at a time registered, except for CX8 which works independent.

Example: Upon the detection of a touch on one of the CX pins, the corresponding TO pin will latch HIGH for the duration of the touch. If a second touch is detected and the change in capacitance created by this touch is bigger than the first touch, it will register as the new touch.

Table 6-4- DIR-C

| Pin State | Input Pins | Output Pins |
|--|-----------------------|-----------------------|
| Button with largest capacitive change is Active High | CX[0,1,2,3, 4,5,6] | TO[0,1,2,3, 4,5,6] |
| Active High | CX8 | TO7 |

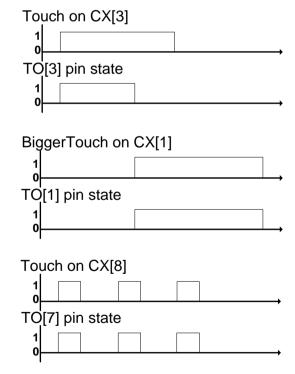


Figure 6-1: DIR-C

6.1.4 DIR-D Minimum Mode (all channels)

Table 6-5- DIR-D

| Pin State | Input Pins | Output Pins |
|--|---------------------------|----------------------------------|
| Button with largest capacitive change is Active High | CX[0,1,2,3, 4,5,6,7,8] | TO[0,1,2,3, 4,5,6,7], BUZZ |

^{*}No buzzer functionality, only logical output

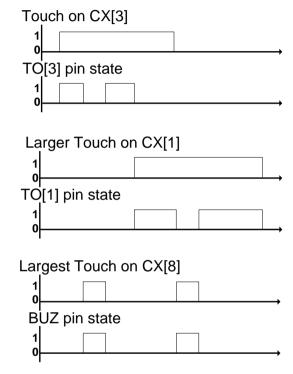


Figure 6-2: DIR-D

6.1.5 DIR-E Minimum Mode (Toggle)

Upon the detection of a touch on one of the CX pins, the corresponding TO pin will toggle HIGH. If a second touch is detected (which creates a larger change in capacitance) on another pin, this pins' corresponding TO pin will toggle HIGH. The pins' state will stay the same, until toggled again.

Only the touch creating the largest change in capacitance to occur is recorded and the corresponding TO pin will toggle HIGH.

Only one touch at a time registered, except for CX8 which works independent.



Table 6-6- DIR-E

| Pin State | Input Pins | Output Pins |
|---|-----------------------|-----------------------|
| Button with largest capacitive change is Toggled High | CX[0,1,2,3, 4,5,6] | TO[0,1,2,3, 4,5,6] |
| Active High | CX8 | TO7 |

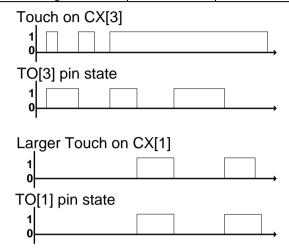


Figure 6-3: DIR-E

6.1.6 DIR-F Toggle Mode

Upon the detection of a touch on pins CX[0,1,2,3,4,5,6,8], the corresponding TO pin will toggle between HIGH and LOW. The pin will stay in that state until toggled again.

Example: If the TO[1] pin is LOW, a touch will change it to HIGH, and also if TO[1] is HIGH, a touch will change it to LOW.

Table 6-7- DIR-F

| Pin State | Input Pins | Output Pins |
|-----------|-------------|-------------|
| Togglo | CX[0,1,2,3, | TO[0,1,2,3, |
| Toggle | 4,5,6,8] | 4,5,6,7] |

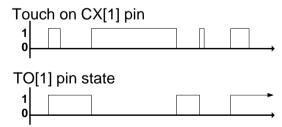


Figure 6-4: DIR-F

6.1.7 DIR-G Current Mode

Upon the detection of a touch on one of the CX pins, the corresponding TO pin will latch HIGH for the duration of the touch. If a second touch is detected on another pin, this pins' corresponding TO pin will latch HIGH and cause the first pins' TO pin to latch LOW. Thus only the latest touch that occurred is recorded. A touch on CX8 will be outputted to the Buzz pin.

Table 6-8- DIR-G

| Pin State | Input Pins | Output Pins |
|--|---------------------------|----------------------------------|
| Last button touched is Active High | CX[0,1,2,3, 4,5,6,7,8] | TO[0,1,2,3, 4,5,6,7], BUZZ |

*No buzzer functionality, only logical output

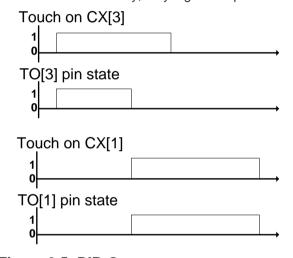


Figure 6-5: DIR-G





Binary Coded Mode

The outputs of these modes are coded in binary to pins TO[3:0]. The '1's and '0's denote logical HIGH and logical LOW irrespectively. See Table 6-9 for the Binary Coded Outputs.

Table 6-9- Binary Coded values

| | TO3 | TO2 | TO1 | TO0 | Decimal |
|-----|-----|-----|-----|-----|---------|
| CX0 | 0 | 0 | 0 | 1 | 1 |
| CX1 | 0 | 0 | 1 | 0 | 2 |
| CX2 | 0 | 0 | 1 | 1 | 3 |
| CX3 | 0 | 1 | 0 | 0 | 4 |
| CX4 | 0 | 1 | 0 | 1 | 5 |
| CX5 | 0 | 1 | 1 | 0 | 6 |
| CX6 | 0 | 1 | 1 | 1 | 7 |
| CX7 | 1 | 0 | 0 | 0 | 8 |
| CX8 | 1 | 0 | 0 | 1 | 9 |

6.1.8 CODED-H Minimum Mode (CX8 independent)

The touch creating the biggest change in capacitance, or in other words pressed with the largest part of the finger will register as the current touch. The channel that registers the largest touch will be outputted to TO[3:0] in binary.

Only one touch at a time registered, except for CX8 which works independent. CX8 is outputted to TO4, and not as displayed in Table 6-9.

Example: Upon the detection of a touch on CX4, the binary coded value '0101'b will be outputted onto TO[3:0]. This value will latch HIGH for the duration of the touch. If a second touch is detected and the change in capacitance created by this touch is bigger than the first touch, it will register as the new touch.

Table 6-10- CODED-H

| Pin State | Input Pins | Output Pins |
|--|-------------------------|-----------------------------------|
| Button with largest capacitive change is Active High | CX[0,1,2,3, 4,5,6,7] | Binary Coded on TO[0,1,2,3] |
| Active High | CX8 | TO4 |

6.1.9 CODED-I Minimum Mode

The touch creating the biggest change in capacitance, or in other words pressed with the largest part of the finger will register as the new touch. The channel that registers the largest touch will be outputted to TO[3:0] in binary.

Only one touch at a time registered. See Table 6-9 for coded values.

Example: Upon the detection of a touch on CX2, the binary coded value '0011'b will be outputted onto TO[3:0]. This value will latch HIGH for the duration of the touch. If a second touch is detected and the change in capacitance created by this touch is bigger than the first touch, it will register as the new touch.

Table 6-11- CODED-I

| Pin State | Input Pins | Output Pins |
|--|---------------------------|-----------------------------------|
| Button with largest capacitive change is Active High | CX[0,1,2,3, 4,5,6,7,8] | Binary Coded on TO[0,1,2,3] |

6.1.10 CODED-J Current Mode

Upon the detection of a touch on one of the CX pins, the corresponding binary value will be outputted to the TO[3:0] pins. The pins will latch HIGH for the duration of the touch. If a second touch is detected on another pin, this pins' corresponding binary value will be outputted to pins TO[3:0], overwriting the first touch's value.

Only the latest touch that occurred is recorded. CX8 operates independently and is outputted to TO4.

Table 6-12- CODED-J

| Pin State | Input Pins | Output Pins | |
|------------------------------------|-------------------------|-----------------------------------|--|
| Last button touched is Active High | CX[0,1,2,3, 4,5,6,7] | Binary Coded on TO[0,1,2,3] | |
| Active High | CX8 | TO4 | |



SPI

The SLAVE SPI protocol is used for serial communication with a MCU. The SPI protocol for the IQS221 has the 4 typical pins used in SLAVE SPI communication:

- ☐ Master out slave in (MOSI) TO1
- ☐ Slave out master in (SOMI) TO2
- □ Serial clock (SCK) TO4
- ☐ Slave Select (/SS) TO5

Additionally a 5th pin is used namely:

□ Ready (RDY) – TO3

The IQS221 should be configured in one of the SPI modes, before SPI communication can commence between the IQS221 and a MCU.

The /SS on the IQS221 must be LOW for it to respond to the MCU (MASTER). This allows the MCU to share the same SPI lines with numerous SLAVES.

The RDY pin is used to alert the MCU that the IQS221 has data available. Only when the MCU sees this, can it clock out a byte from the IQS221. The RDY pin will go low for every byte of data it has available.

The RDY line is driven LOW by the IQS221 after the first rising edge of the SCK from the MCU, and will only go HIGH again when the next data byte is available.

The MCU SPI should be set up so that:

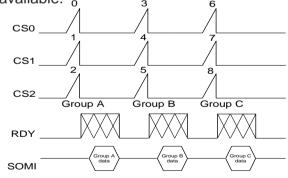
- ☐ The MCU is MASTER
- ☐ The MCU waits for RDY to be HIGH before initiating the data transfer
- ☐ Input data (SOMI) is sampled at end of data output time
- □ Data transmission occurs on the rising edge of the clock (SCK)
- ☐ Idle state for clock is a HIGH

The SPI timing is illustrated in Figure 6-7. The data for groups A, B and C are sent after the conversions for the relevant group are complete.

Example: The data for CX0, CX1 and CX2 are sent together, and in the next cycle the data for CX3, CX4 and CX5 are sent together. Refer to Figure 6-6.

The following functions differ when the IC operates in a SPI mode:

- OPT2 This pin can be used to wake up the IQS221 / continue data transfer with the IQS221, after a SLEEP / STOP_TRANSMIT command. A falling edge will wake the IQS221
- Sensitivity selections are internal and set through SPI commands.
- □ TO4 This selection should be sent via a SPI command.



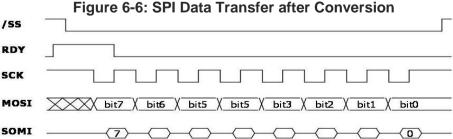


Figure 6-7: SPI Timing





6.1.11 SPI-L Relative Values

Relative values of each channel are sent via SPI. The relative values are derived from the raw data of each channel normalised with the filter value of the same channel. This relative value gives the designer the ability to see which channel gives the largest change with a user touch.

If the Count is exactly the same as the filter value, then the value sent would be 256. The bigger the touch/proximity, the smaller this value would become. In this mode a SPI string of 12 bytes is sent out in a cycle. The 12 bytes are indicated in Table 6-13.

Table 6-13- SPI-L - Description of Bytes sent

| | | Bytes Sent by IQS221 | | Bytes Received by IQS221 | |
|--------|-------|------------------------------------|----------------------|--------------------------|-------------------|
| Byte # | Bit # | Value | Function | Value | Function |
| 1 | 7:0 | 0xFF | Header1 | Command Header | Note ⁵ |
| 2 | 15:8 | <nd cba=""><cba><d></d></cba></nd> | Header2 ¹ | Command Data | Note ⁵ |
| 3 | 23:16 | CH[7:0] ² | Active channels | Length | Note ⁶ |
| 4 | 31:24 | Relative I | MSB | D/C | Don't care |
| 5 | 39:32 | Relative I | LSB | D/C | Don't care |
| 6 | 47:40 | Relative II | MSB | D/C | Don't care |
| 7 | 55:48 | Relative II | LSB | D/C | Don't care |
| 8 | 63:56 | Relative III | MSB | D/C | Don't care |
| 9 | 71:64 | Relative III | LSB | Length | Note ⁶ |
| 10 | 79:72 | ThresholdX | Note ³ | D/C | Don't care |
| 11 | 87:80 | ThresholdY | Note ³ | D/C | Don't care |
| 12 | 95:88 | CRC | Note ⁴ | D/C | Don't care |



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6.1.12 SPI-M Raw Data Out

Count and filter values of each channel is sent Table 6-14.

The SPI functionality is identical to that described above in Section 6.1.11, with the

addition of a LENGTH byte = 0x04 sent to stop the SPI after byte 15.

as Raw data via SPI. The designer has the For both SPI modes, if a proximity is detected freedom to implement a custom User Interface on any of the channels, POUT will latch HIGH using a MCU. The data is sent according to for the duration of the proximity event, the Buzz also functions on a TOUCH.

Table 6-14- SPI-M - Description of Bytes sent

| | | Bytes Sent by IQS221 | | Bytes Received by IQS221 | | |
|--------|---------|------------------------------------|----------------------|--------------------------|-------------------|--|
| Byte # | Bit # | Value | Function | Value | Function | |
| 1 | 7:0 | 0xFF | Header1 | Command Header | Note ⁵ | |
| 2 | 15:8 | <nd cba=""><cba><d></d></cba></nd> | Header2 ¹ | Command Data | Note ⁵ | |
| 3 | 23:16 | CH[7:0] | Active channels | Length | Note ⁶ | |
| 4 | 31:24 | CSI | MSB | D/C | Don't care | |
| 5 | 39:32 | CSI | LSB | D/C | Don't care | |
| 6 | 47:40 | CS II | MSB | D/C | Don't care | |
| 7 | 55:48 | CS II | LSB | D/C | Don't care | |
| 8 | 63:56 | CS III | MSB | D/C | Don't care | |
| 9 | 71:64 | CS III | LSB | Length | Note ⁶ | |
| 10 | 79:72 | LTI | MSB | D/C | Don't care | |
| 11 | 87:80 | LTI | LSB | D/C | Don't care | |
| 12 | 95:88 | LT II | MSB | D/C | Don't care | |
| 13 | 103:96 | LT II | LSB | D/C | Don't care | |
| 14 | 111:104 | LT III | MSB | D/C | Don't care | |
| 15 | 119:112 | LT III | LSB | Length | Note ⁶ | |
| 16 | 127:120 | ThresholdX | Note | D/C | Don't care | |
| 17 | 135:128 | ThresholdY | Note | D/C | Don't care | |
| 18 | 143:136 | CRC | Note | D/C | Don't care | |

Note1: <ND> = Set when Noise Detected Note2: configuration bits – default enabled)

<CBA>= Touch(III);Touch(II);Touch(I)

 $\langle cba \rangle = Prox(III); Prox(II); Prox(I)$

<d>= Channel 8 active

Example: If Group A data is being sent (CX0, CX1 and CX2), and a touch is detected on CX1 and CX2: then $\langle CBA \rangle = 110$.

Along with bit 'd' sent in Byte #2, (Noise Detection scheme must be enabled in these 9 bits indicate which 3 channels' data is sent in Byte #4 - #9. If one of the channels in this group is disabled, the bit would be = 0.

> Example if Group A data is being sent (CX0, CX1 and CX2); then d=0 and Byte #3 = 00000111.

Table 6-15: Note3:

| | bit7 | bit6 | bit5 | bit4 | bit3 | bit2 | bit1 | bit0 |
|------------|----------------|------|------|------|------|--------|--------|--------|
| ThresholdX | PROXL VLSEL | TO7 | TO6 | TO5 | TO4 | TO2 | TO1 | TO0 |
| | | | | | | | | |
| ThresholdY | Х | Х | Х | Х | Х | halt C | halt B | halt A |





ThresholdX: The current sensitivity settings as decoded in Table 6-21 to Table 6-24 are shown. PROXLVLSEL - This overwrites the status of Alternative PROX level selection OTP bit.

ThresholdY: Indicates the state of the respective filter, whether it is being halted from the IQS221

Note4: The CRC byte is a simple XOR of all the bytes sent, this can be used together with the header for synchronising, as well as confirmation that all data was transmitted correctly.

Note5: Data can be sent to the IQS221 to adjust a variety of settings. These commands can be decoded as:

Table 6-16: SPI Commands

| SPI Command | Function |
|-------------|---------------------|
| 0xE1 | Prox/Touch settings |
| 0xB4 | Configuration |
| | settings |
| 0xD2 | Command settings |

Example: Overwriting the sensitivity settings can be achieved by sending a command header = E1, and then data in the same formatting as ThresholdX. See Table 6-18 below.

Note6: The length packet determines the number of bytes sent out in the SPI cycle. Once the length byte is received, the IQS221 will adjust the number of bytes it sends out immediately, followed by the CRC byte.

Table 6-17: Length Packet

| Length byte | Interrupt at: |
|-------------|------------------------|
| 0x00 | No interrupt |
| 0x01 | Interrupt after Byte3 |
| 0x02 | Interrupt after Byte9 |
| 0x04 | Interrupt after Byte15 |

Table 6-18: ThresholdX data

| Command | 0xE1 | | | | | | | |
|---------|----------------|------|------|------|------|------|------|------|
| | bit7 | bit6 | bit5 | bit4 | bit3 | bit2 | bit1 | bit0 |
| Data | PROXLVL SEL | TO7 | TO6 | TO5 | TO4 | TO2 | TO1 | TO0 |

bit7 PROXLVLSEL: PROX Level select control bit (See Section 6.3)

1 = enable alternative Proximity level selection

0 = default

bit6:0 **TO7:TO0**: TO pins' state control bits (See Section 6.3)

Table 6-19: Configuration Settings

| Command | | 0xB4 | | | | | | | |
|--|--|------------------|------------|--------------|---------------------------|--------------|-----------|------|--|
| | bit7 | bit6 | bit5 | bit4 | bit3 | bit2 | bit1 | bit0 | |
| Data | SHIELD | ZOOM | HALT1 | HALT0 | FASTCH | LP1 | LP0 | XLP | |
| | | | | | ARGE | | | | |
| bit7 | bit7 SHIELD: Shield enable/disable control bit (See Section 8) | | | | | | | | |
| 1 = enable Shield | | | | | | | | | |
| | 0 = disable shield | | | | | | | | |
| bit6 | 2 | ZOOM: Zoo | m enable/d | isable contr | ol bit (See S | Section 6.8) | | | |
| | | 1 = disable Zoom | | | | | | | |
| 0 = enable Zoom | | | | | | | | | |
| bit5:4 HALT1/HALT0 : Halt filter time-o | | | | er time-out | (T _{HALT}) sele | ct (See Sec | tion 6.7) | | |
| | | 11 = Always halt | | | | | | | |
| | | 10 = Never halt | | | | | | | |





01 = 40s00 = 20s

bit3 FASTCHARGE: Fast charge enable/disable control bit (See Section 6.6)

1 = enable Fast charge ($T_{SAMPLE} = \pm 15ms$) 0 = disable Fast charge ($T_{SAMPLE} = \pm 20ms$)

bit2:1 LP1/LP0: Low power mode select (only used if OPT1 = LOW or set with

Command 0xD2) (See Section 6.5)

11 = 440ms 10 = 330ms 01 = 220ms 00 = 110ms

bit0 **XLP** = Additional Low power Mode enable/disable control bit

1 = enable XLP 0 = disable XLP

Table 6-20: Command settings

| Command | 0xD2 | | | | | | | |
|---------|-------|------|------|-------|-------|-------|------|---------|
| | bit7 | bit6 | bit5 | bit4 | bit3 | bit2 | bit1 | bit0 |
| Data | RESEE | - | - | NP/LP | SLEEP | STOPS | ND | CONVDIV |
| | D | | | | | PI | | |

bit7 RESEED: Force a filter reseed to 8 counts below count

1 = force RESEED on filter

0 = filter unaffected

bit6 Unused bit5 Unused

bit4 NP/LP: Normal power / Low power mode select

1 = Low power mode0 = Normal power mode

bit3 **SLEEP**: Sleep enable/disable control bit⁷

1 = enable Sleep 0 = IQS221 unaffected

bit2 **STOPSPI**: Stop SPI communication enable/disable control bit⁸

1 = enable STOPSPI 0 = IQS221 unaffected

bit1 **ND** = Noise Detect enable/disable control bit

1 = disable ND 0 = enable ND

Bit0 **CONVDIV** = Set the conversion frequency (See Section 6.9)

1 = 125kHz (nominal) 0 = 250kHz (nominal)

Writing of values is optional. If no valid command header is received, the values are ignored.

Note7: If IQS221 receives a SLEEP instruction from the master, the conversions will stop once the current group of conversions is finished and the serial communications halted.

The device can only be woken by a falling edge on OPT2 from the master.

Once the IQS221 wakes up, the charge conversions and serial communication can continue. The master must sample the RDY line which will indicate when the slave is ready to transmit data again.

Note8: Once the IQS221 receives a STOPSPI instruction from the master the current cycle of serial communication will complete, then all communication will stop.





Please note that an external pull-down will be required, to keep the OPT2 line in a defined state during this time. The serial communication can then resume on one of the following two ways:

- a.) If a proximity is detected by the IQS221, the RDY line will go HIGH to indicate to the master that serial communication can resume.
- b.) The master must indicate to the slave that it's ready to resume serial communications by pulling /SS LOW (as is normal for selecting a device). Then it must wait for the RDY as usual to know when data is available.

To allow the SLEEP & STOPSPI to be controlled by the master the /SS & OPT2 can be connected together externally, giving the master the ability to wake the IC from sleep and resume communications without the need for an extra I/O.

6.2 Disabling Channels

Disabling a channel is done with a PULL-Down resistor on the CX pin that should be disabled to GND. Typical values used for PULL-Down resistors are $10k\Omega$.

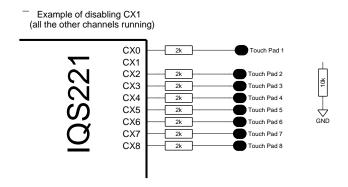


Figure 6-8: Disable CX1



Azoteg

6.3 Sensitivity Settings

3 methods to adjust the sensitivity of a device exist:

- ☐ Resistors on the pins TO0, TO1, TO2, TO4, TO5, TO6 and TO7
- □ Internally on OTP bits (except TO4) discarding the need for resistors
- ☐ All settings can also be set through SPI commands

An option exist (configurable with the OTP Configuration Bits) to choose between using the external (default) or internal sensitivity options. The selection values are determined at POR and used for as long as power is supplied to the IQS221. See section 6.1.11 for SPI output mode sensitivity selections (internal selection is default in SPI).

Proximity / Touch Detection: measured values are compared with the LTA values for each channel. A Proximity or Touch condition will register if the difference between the measured value and LTA Average value are equal to or bigger than the sensitivity level selected.

sensitivity level The proximity determined by a change of a fixed amount of capacitance whilst a Touch is registered if the measured value changes by a specified fraction of the Average Filter Value.

Touch Sensitivity (external): Touch threshold values are specified in Table 6-21 & Table 6-22. The touch threshold values for CX[7:0] are the same while CX[8] can be adjusted independently. ΑII selections are performed on the TO pins when not in SPI mode. The designer has a choice between four touch sensitivity levels for CX[8:0]. CX8 has an independent touch sensitivity setting.

Proximity Sensitivity (external): The Proximity threshold values are specified in Table 6-23 & Table 6-24. The proximity threshold values for CX[7:0] are determined by a combination of the states of the TO3 and TO5 pins, while the threshold values for CX[8] are determined by the states of TO6 and TO7.

The proximity threshold values for CX[7:0] are the same while CX[8] can be adjusted independently. All selections are performed on the TO pins when not in SPI mode.

The designer has a choice between five proximity sensitivity levels for both CX[7:0] and CX[8].

Green Font selections User are Selectable with OTP bits and can be directly related to the USBProg.exe program.

Table 6-21: CX[7:0] Touch Sensitivity

IQ Switch®

| T01 | TO0 | Sensitivity Level (C _△) |
|------|------|-------------------------------------|
| LOW | LOW | A (1/32) |
| LOW | HIGH | C (2/16) |
| HIGH | LOW | B (1/16) |
| HIGH | HIGH | D (3/16) |

Table 6-22: CX8 Touch Sensitivity

| TO4 | TO2 | Sensitivity Level (C _△) |
|------|------|-------------------------------------|
| LOW | LOW | A (1/32) |
| LOW | HIGH | C (2/16) |
| HIGH | LOW | B (1/16) |
| HIGH | HIGH | D (3/16) |





| Table 6-23: Channel | [7:0] - | TO5 | | | |
|------------------------------|-------------|--------|-------------|--|--|
| Proximity Sensitivity | level | Low | High | | |
| PROX Level | Default | H (6) | F (2) | | |
| Selection | Alternative | I (12) | L (disable) | | |

| Table 6-24: Channel 8 - | | T07 / T06 | TO7 / TO6 | T07 / T06 | T07 / T06 |
|-----------------------------|-------------|-----------|------------|------------|-------------|
| Proximity Sensitivity level | | LOW / LOW | LOW / HIGH | HIGH / LOW | HIGH / HIGH |
| PROX Level | Default | H (6) | I (12) | G (4) | F (2) |
| Selection | Alternative | J (16) | E (1) | K (32) | L (disable) |



Figure 6-9: Touch Sensitivity Scale

Figure 6-10: Proximity Sensitivity Scale

Internal Selections: These options are only used if the EXT/INT Sensitivity Selection bit is configured to Internal with the OTP Configuration Bits. The selections are as shown in Table 6-25 to Table 6-28.

Green Font selections are OTP bits and can be directly related to the USBProg.exe program.

Table 6-25: Channel [7:0] - Internal Touch Sensitivity

| CH[7:0] - Internal TOUCH Sensitivity Level (C _△) | Sensitivity Level* |
|--|--------------------|
| Level 1 (Most Sensitive) {default} | A (1/32) |
| Level 2 | B (1/16) |
| Level 3 | C (2/16) |
| Level 4 (Least Sensitive) | D (3/16) |

| Table 6-26: Channel 8 - Internal Touch | T | 04 |
|---|----------|----------|
| Sensitivity level (C _△) | LOW | HIGH |
| CH8 – Internal TOUCH Sensitivity: {default} | A (1/32) | B (1/16) |
| CH8 – Internal TOUCH Sensitivity: | C (2/16) | D (3/16) |

| Table 6-27: Channel [7:0] - Proximity | PROX Lev | PROX Level Selection | | |
|---------------------------------------|----------|----------------------|--|--|
| Sensitivity Level (C _△) | Default | Alternative | | |
| Prox[7:0]: {default} | H (6)** | I (12) | | |
| Prox[7:0]: | F (2) | L (Disable) | | |

| Table 6-28: Channel 8 - Proximity Sensitivity | PROX Lev | el Selection |
|---|----------|--------------|
| Level (C _∆) | Default | Alternative |
| Prox[8]: Level 1 (Most Sensitive) | F (2) | L (Disable) |
| Prox[8]: Level 2 {default} | H (6) | J (16) |
| Prox[8]: Level 3 | G (4) | K (32) |
| Prox[8]: Level 4 (Least Sensitive) | l (12) | E (1) |

^{*}Refer to Figure 6-10 and Figure 6-9

^{**}Please refer to APP Note: "AZD006 – VisualProxSense Overview" for details regarding sensitivity and levels





6.4 Additional Low Power Mode

This option is user configurable with the OTP Configuration Bits. See Section 4 for more details regarding the programming of the OTP bits.

Using this feature enables the designer to implement a semi-sleep mode in the IQS221.

This feature entails that if no proximity has been detected for 50s or more, all channels except CX8 will seize charging. CX8 will continue to charge according to the original chosen time basis.

The other channels will now only be charged every 3s to keep the relevant filters updated. With the detection of a proximity condition on CX8, the conversions of the other channels will resume at the normal conversion rate.

This mode can be used in conjunction with the LP Modes or stand-alone.

6.5 Charge Period in Low Power (LP) Mode

Choosing a Power Mode

The IQS221 IC has four power modes. The low power modes are specifically designed for battery applications and applications not requiring immediate responses.

The Low Power Modes are selected dynamically by polling the OPT1 Pin LOW. See section 6.10.1 for more details.

The different Power Modes are user configurable with the OTP Configuration Bits. Please see Section 4 for more details regarding the programming of the OTP bits.

The different power modes control the duty cycle between charge transfers (TLP). Refer to Section 5 for more details on the charge transfers. The timings (TLP) given in Table 6-30 are measured from the end of the first conversion to the start of the following conversion. See Figure 6-11.

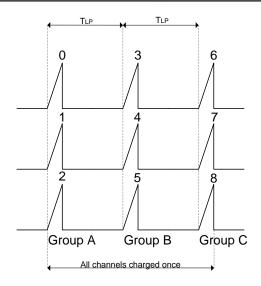


Figure 6-11: Measurement of TLP

Table 6-29: LP Timings

| Power Mode | Timing* (T _{LP}) |
|------------|-------------------------------|
| LP1 | 110ms |
| LP2 | 220ms |
| LP3 | 330ms |
| LP4 | 440ms |

^{*}Timings are approximate

6.6 Fast Charge Selection

Conversions are done at a default rate $(T_{\text{SAMPLE}} - \text{See section 5})$ in NP Mode. Enabling the Fast Charge Selection enables the CS conversions to occur at a faster rate.

Choosing the Fast Charge selector, improves response time, but could result in slightly higher power consumption.

This option is user configurable with the OTP Configuration Bits. Please see Section 4 for more details regarding the programming of the OTP bits.

6.7 Long Term Average (LTA) Filter & using T_{HALT}

The IQS221 has a built-in IIR filter that is capable of intelligently tracking changes in the environment. The filter is implemented on each channel independently.



The filter calculates the average value (Long Term Average (LTA)) of the measurements. The LTA values are compared to the Measured values (Count (CS)) to determine if a proximity or physical contact activity has occurred. If a difference of $C_\Delta^{\ 3}$ is found between the LTA and CS value a proximity or physical contact activity is recorded. The applicable channel responds to this detected activity and the IIR Adaptation Filter freezes to keep the LTA value as reference.

Halting the filter: T_{HALT} is user configurable with the OTP Configuration Bits. Please see Section 4 for more details regarding the programming of the OTP bits.

Table 6-30: Filter Adaptation Conditions

| T _{HALT} | Filter |
|-------------------|--------------------------------|
| 20s | Filter halts for 20s, and then |
| (default) | recalibrate |
| 40s | Filter halts for 40s, and then |
| 405 | recalibrate |
| Never | Filter Adaptation NEVER halts |
| Always | Always halt filter |

^{*}Timings are approximate

How the filter works: With the detection of a proximity the LTA filter freezes for T_{HALT} , as indicated in Table 6-30. If this proximity condition is maintained for longer than T_{HALT} , the relevant channel will be recalibrated and its outputs reset. This is implemented to adapt to a rapid change in the environment and prevent a permanent stuck condition.

With the detection of a touch condition, the T_{HALT} counters will reset, and re-start the halting of the channels' filters (the system will thus not loose sensitivity while operated by a user).

6.8 Zoom Option

The Zoom mode is default enabled but the Zoom mode is only available if the

 3 C_{Δ} = Change in Capacitance: Determined by sensitivity settings

Low Power (LP) Mode is selected (dependent on OPT1, See Section 6.10.1). In the LP mode, conversions are done according to T_{LP} in Table 6-29.

With the detection of a proximity, the conversion rate zooms in to the NP Mode (TSAMPLE). Operation then occurs in the zoomed in state for TZOOM after the last proximity has been detected. When TZOOM is timed out, the conversions are done according to the LP timing selections once again.

The different Zoom Modes are user configurable with the OTP Configuration Bits. See Section 4 for more details regarding the programming of the OTP bits.

6.9 Conversion Divider

The frequency of the charge transfers occur nominally at 250kHz. Enabling the conversion divider with an OTP bit (or through a serial command) will divide the frequency of charge transfers by 2 (changing it to 125kHz), effectively doubling the conversion rate.

This will result in a slower response time, and more current consumption, but is advantageous when an extremely large sense electrode is used, and the charge transfers can not be completed with the normal transfer rate. See the application note: "AZD004 - Azoteq Capacitive Sensing" for a complete description of the advantage of this feature.

6.10 Dynamic User Options

Table 6-31: Dynamic options

| | HIGH | LOW |
|-----------------|-------------|-----------|
| OPT1 LP / NP | NP | LP |
| OPT2 | Halt Charge | Normal |
| HC / RDY | Transfers | Operation |

6.10.1 OPT1 - LP/NP Mode Operation

The OPT1 Pin is used to dynamically toggle (with MCU), or fix (with resistor) between Normal Power and Low Power Mode. If OPT1 is LOW, the conversions



are determined by the LP mode and thus the selections made in Table 6-29. If OPT1 is HIGH, the conversion rate is T_{SAMPLE} (dependent on selection made in section 6.6).

6.10.2 OPT2 - HC / RDY Operation

The IQS221 issues a RDY signal after all the channels have completed a charge transfer, thus after every Group C conversion in section 6.5.

The charge transfers on the IQS221 IC can be dynamically halted (Halt Charge (HC)) by polling the OPT2 Pin HIGH with a MCU. If this signal occurs during a group of conversions, the group will finish its conversions and the following conversions on the IQS221 will be halted until the OPT2 Pin is Polled LOW again.

7 Zero Cross Function

The ZC Pin is used by the IQS221 to synchronise with AC. This enables the IC to do charge transfers synchronised to AC, which entails the charge transfers occurring at 20ms intervals (nominally). Otherwise the IQS221 will run at its internal clock frequency. If ZC function is not used, the ZC pin should be tied to ground through a $100k\Omega$ resistor.

Using this function greatly enhances stability of the system, which in turn improves the proximity detection distance.

Typical values for current protection resistors when synchronising to $220V_{AC}$ is 2 x $510k\Omega$. When synchronising to any other device and the synchronization pulses exceed VDDHI, current protection resistors should be used.

8 Shield Function

The IQS221 has a shielding function built-in. Advantages of the shield:

☐ The shield enables the user to separate the Sensing Electrode from

the sealed electronics

- ☐ The shield enables the designer to shield the sensing wire from unwanted environmental interference like water passing in a water pipe or people passing over the sense wire.
- The shield enhances proximity detection when used with battery (DC) applications.

Connecting the Shield

Ideally, a Coaxial cable is used for the shield. A Rx (nominally $2k\Omega$) resistor should be connected to the Cx pin, and the other side of the Rx resistor is connected to the Centre Core. This node is also connected to the SHLDIN pin. The SHLDOUT pin should be connected to the Metallic Shield part of the Coaxial cable. A pull-up resistor (R) should be added between SHLDOUT and VDDHI ($100k\Omega \le R \le 1M\Omega$). NOTE: Smaller R ensures better shielding but increases current usage.

The typical Cx channel used to shield is Cx8, as it is able to operate independently (Cx8 has an independent sensitivity setting). See Figure 8-1 for a more detailed explanation.

 $VDDHI_{(MIN)} = 4.7V$ when using the Shield function.

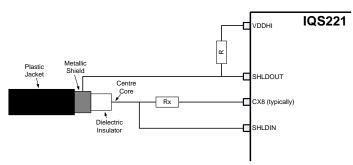


Figure 8-1: Connecting the Coaxial Cable

9 Additional Features

9.1 Buzzer

The IQS221 gives the designer the ability to employ a Buzzer by outputting an applicable signal onto the Buzz pin. This signal will not be outputted to some of



the Output Modes. (See Section 6.1 for more details).

The Buzzer will function as follows: Upon the detection of a touch the Buzzer will click once, and if the touch persists, the Buzzer will have a small delay where after it will have a repetitive click. (Toggle Output Mode will only click when an Output Pin changes state).

DC Buzzer

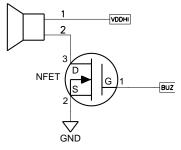


Figure 9-1: Typical DC Buzzer Connection

9.2 RF Noise Immunity and Detection

The IQS221 has advanced immunity to high power RF noise, typically transmitted by GSM cellular telephones, DECT, Bluetooth and WIFI devices. Design guidelines can be followed to help with the noise immunity:

- □ A ground plane should be placed under the IC, except under the CX lines
- All the tracks on the PCB must be kept as short as possible.
- The capacitor between VDDHI and VSS as well as between VREF and VSS, must be placed as close as possible to the IC.
- A 100 pF capacitor can be placed in parallel with the 1uF capacitor between VDDHI and VSS. Another 100 pF capacitor can be placed in parallel with the 1uF capacitor between VREF and VSS.

It is still possible for a condition to exist with the transmitter placed in extreme close proximity to the IC that the IC might react to this transmitted power. The Noise Detection feature should be used

for these applications (It is default enabled, but can be disabled with an OTP Configuration Bit).

For this exception, the IQS221 has a built-in Noise Detection scheme. The IQS221 is thus able to detect Cellular telephone noise or any other high power transmitted noise on the RFIN pin.

For this function the RFIN pin would require an external antenna mounted, to increase efficiency of noise detection. The details of the aforementioned antenna can be seen in Application Note: "AZD015 – RF Immunity and detection in ProxSense devices".

With the detection of noise, the IQS221 will halt, keeping all outputs in the same state as they were before noise was detected. The Noise Detection scheme can be disabled if needed with an OTP Configuration Bit.



10 Reference Designs

10.1 SPI Design Example

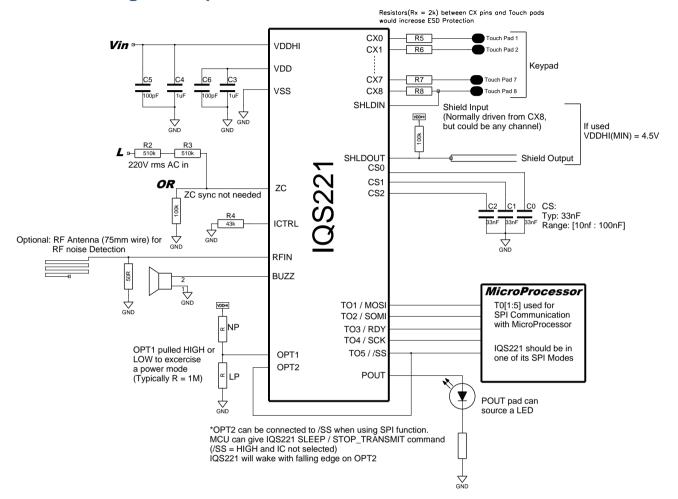


Figure 10-1: SPI Design



10.2 Direct Design Example

IQS221 in one of its Direct or Binary Coded Modes

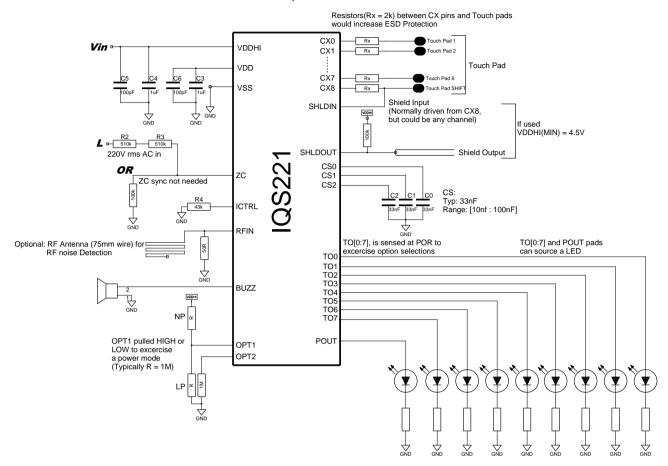


Figure 10-2: Direct Design



11 Specifications

11.1 Absolute Maximum Specifications

Exceeding these maximum specifications may cause damage to the device.

 $\begin{array}{lll} \text{Operating Temperature} & \text{O°C to 70°C} \\ \text{Supply Voltage (V_{DDHI}, - V_{SS})} & 5.5V \\ \text{Maximum Pin Voltage (V_{DD}, POUT, TOx, OPT2)} & V_{DDHI} + 0.5V \\ \text{Pin Voltage (CS, CX)} & 2.5V \\ \text{Minimum Pin Voltage (V_{DDHI}, V_{DD}, POUT, CS, CX)} & V_{DDHI} - 0.5V \\ \text{Minimum Turn On Slope} & 10V/s \\ \text{ESD Protection (All Pads)} & 2kV \\ \end{array}$

11.2 Operating Conditions (Measured at 25°C)

Table 11-1: Operating conditions

| DESCRIPTION | PARAMETER | MIN | TYP | MAX | UNIT |
|--|------------------------------|----------------|-----------------------|-------------------|------|
| Internal Regulator Output ⁴ | V_{DD} | 2.2 | 2.5 | 2.8 | V |
| Supply Voltage Input (No Shield Implemented) | V_{DDHI} | 3 | 5 | 5.5 | V |
| Supply Voltage Input (Shield implemented) | V_{DDHI} | 4.7 | 5 | 5.5 | V |
| Normal Operating current ⁵ | I _{IQS221_NORMAL} | | 195 | | μΑ |
| Low Power Operating current ⁶ | I _{IQS221_LOWPOWER} | | 27 | | μΑ |
| CS trip voltage | V_{TRIP} | 600 | 730 | 785 | mV |
| Zero cross input voltage | V_{ZC} | $0.9*V_{DDHI}$ | V_{DDHI} | $V_{DDHI} + 0.5V$ | V |
| POUT High Voltage | V _{POUT_HIGH} | | V_{DDHI} | | V |
| Input Low Voltage on pins TO[0:4], TO2 | V _{IL} | | 0.1*V _{DDHI} | | V |
| Input High Voltage on pins TO[0:4], TO2 | V _{IH} | | 0.9*V _{DDHI} | | V |

11.3 Output Characteristics

Table 11-2: Output Pins (POUT, TO[7:0], Buzz) Characteristics

| Symbol | Description | Doromotor | Conditions | IQS221 | | | UNIT |
|-----------------|-----------------|---------------------------|-------------------|--------|------|-----|------|
| Symbol | Description | Parameter | Conditions | MIN | TYP | MAX | UNIT |
| | Output | $I_{SOURCE} = 6mA$ | $V_{DDHI} = 5V$ | | 4 | | |
| V _{OH} | High Voltage | I _{SOURCE} = 4mA | $V_{DDHI} = 3.3V$ | | 2.3 | | V |
| V | Output Low | $I_{SINK} = 9mA$ | $V_{DDHI} = 5V$ | | 1.25 | | |
| V _{OL} | Voltage | $I_{SINK} = 5mA$ | $V_{DDHI} = 3.3V$ | | 0.9 | | |

Note 4: $V_{DDHI} = 5V$

Note 5: V_{DDHI} = 5V, Charge Cycle Duration < 10ms in Normal Power Mode

Note 6: V_{DDHI} = 3V, Charge Cycle Duration < 10ms in LP4



11.4 Timing Characteristics

Table 11-3: Timing Characteristics

| DESCRIPTION | SYMBOL | | IQS221 | | |
|---------------------------------------|----------------------------|------------------|--|-----|------|
| DESCRIPTION | | | TYP | MAX | UNIT |
| Output Minimum High Time on TO pins | T _{HIGH} | | 60 | | ms |
| Output pins' latching time | T _{LATCH} | | 3 | | S |
| Time before switching back to LP Mode | T _{ZOOM} | | 3.3 | | S |
| CX charging Oscillator ⁷ | F _{CX} | 213 | 250 | 287 | kHz |
| Filter Freeze Condition | T _{HALT} | | Refer to Table 6-30 | | S |
| Charge Cycle Delay Time ⁸ | T _{SAMPLE} | 15 ⁹ | 20 | 22 | ms |
| Low Power Delay Time | T_{LP} | | Refer to Table 6-29 | | ms |
| Touch Response Time | $T_{DEBOUNCE.Touch}$ | 30 ¹⁰ | 120 ¹¹ | | ms |
| Proximity Response Time | T _{DEBOUNCE.Prox} | 60 ¹⁰ | 240 ¹¹ | | ms |
| Charge Times | T _{CHARGE} | | Determined by C _S Capacitor | | ms |

11.5 Moisture Sensitivity Level

Moisture Sensitivity Level (MSL) relates to the packaging and handling precautions for some semiconductors. The MSL is an electronic standard for the time period in which a moisture sensitive device can be exposed to ambient room conditions (approximately 30°C/60%RH) before reflow occur.

Table 11-4: MSL

| Package | Level (duration |
|-----------|-------------------|
| SO-32 | MSL 3 (168 hours) |
| QFN5x5-32 | MSL 3 (168 hours) |

Note 7: Enabling Conversion Divider (with OTP bit 20) will divide F_{CX} by 2

Note 8: Time for One Charge Cycle if T_{CHARGE} < 20ms

Note 9: Fast Charge Selection Enabled (See Section 6.6)

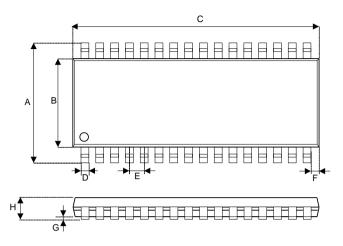
Note 10: CS < 10ms and only 1 Group active – 3 channels (See Figure 5-1)

Note 11: CS < 10ms and all Channels active





12 Packaging Information





SO-32 Packaging¹²

Table 12-1: SO-32 Dimensions

| Dimension | Min | Max | |
|-----------|-----------------|----------|--|
| Α | 10.2 mm | 10.6 mm | |
| В | 7.42 mm | 7.62 mm | |
| С | 20.88 mm | 21.08 mm | |
| D | 0.3 mm | 0.5 mm | |
| E | 1.27 r | nm typ | |
| F | 0.77 r | nm typ | |
| G | 0.1 mm | 0.25 mm | |
| Н | 2.14 mm 2.34 mn | | |
| I | 4° typ | | |
| J | 0.55 mm | 0.95 mm | |

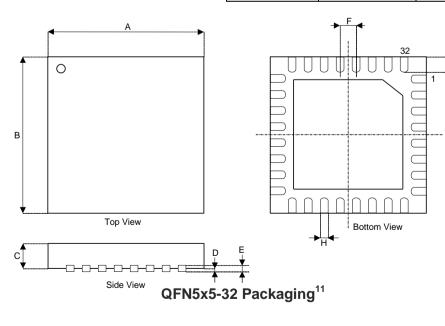


Table 12-2: QFN5X5-32 Dimensions

| Dimension | Min | Max |
|-----------|----------|----------|
| Α | 4.900 mm | 5.100 mm |
| В | 4.900 mm | 5.100 mm |
| С | 0.700 mm | 1.000 mm |
| D | 0.000 mm | 0.050 mm |
| Е | 0.178 mm | 0.228 mm |
| F | 0.450 mm | 0.550 mm |
| G | 0.300 mm | 0.500 mm |
| Н | 0.180 mm | 0.300 mm |

¹² Drawing not on Scale

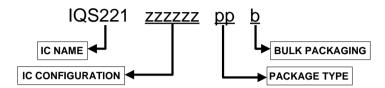


13 Datasheet and Part-number Information

13.1 Ordering Information

For large orders, Azoteg can provide pre-configured devices.

The Part-number can be generated by using USBProg.exe or the Interactive Part Number generator in the ProxSense -> Multiple Channel section of www.azoteg.com. Contact distributor for smaller quantities.



IC CONFIGURATION IC Configuration (hexadecimal) ZZZZZZ =

PACKAGE TYPE QN QFN5x5-32 (Quad Flat Package No Leads)

> SO-32/SOIC 32 Pin (Small Outline Package) SO

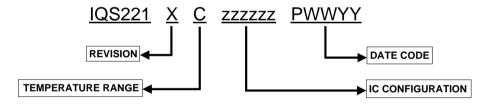
BULK PACKAGING QFN5x5-32: R Reel (3000pcs/reel)

> SO-32: Tube (20pcs/tube) - MOQ = 1200pcs

IQS221 008B28 QN R = IQS221 IC in configuration 008B28, packaged in QFN5x5-32 **Example:**

package and shipped in a Reel

13.2 Device Packaging Convention



REVISION Χ IC Revision Number

TEMPERATURE RANGE С 0°C to 70°C (Commercial)

-40°C to 85°C (Industrial)

IC CONFIGURATION IC Configuration (hexadecimal) ZZZZZZ =

DATE CODE Р Package House

> WW Week ΥY Year

IQS221 2C 008B28 12308 = Revision 2; Commercial Temperature Range; Output Configuration 008B28; Packaged at House 1 the 23RD week of 2008 Example:





13.2.1 Batch Numbering for Pre-Production Samples

| Batch Number | Description |
|-------------------------------------|--|
| IQS221ENG E5 / D5 / D6 | Engineering run #1 |
| IQS221PPS E7 | Pre-Production Sample #0 (SO-32 and QFN5x5-32) |
| IQS221PPS E11 (or Date Code: x2009) | Pre-Production Sample #1 (SO-32 and QFN5x5-32) |
| IQS221 1C zzzzzz PWWYY | First Production version |

| 13.3 Datasheet Revision History |
|---|
| Version 4.00 |
| ☐ First production version datasheet |
| Version 4.01 |
| ☐ Inserted Section 11.5 |
| Version 4.02 |
| □ Updated MOQ for QFN5x5-32 Reel quantity to 3000pcs/reel |
| Version 4.03 |
| □ Corrected MSL data |
| Version 4.04 |
| ☐ Corrected package marking orientation on figures |





14 Contact Information

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The following patents relate to the device or usage of the device: US 6,249,089 B1, US 6,621,225 B2, US 6,650,066 B2, US 6,952,084 B2, US 6,984,900 B1, US 7,084,526 B2, US 7,084,531 B2, US 7,265,494 B2, US 7,291,940 B2, US 7,329,970 B2, US 7,336,037 B2, US 7,443,101 B2, US 7,466,040 B2, US 7,498,749 B2, US 7,528,508 B2, US 7,119,459 B2, EP 1 120 018 B1, EP 1 206 168 B1, EP 1 308 913 B1, EP 1 530 178 B1, ZL 99 8 14357.X, AUS 761094

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