



### **GENERAL DESCRIPTION**

The EM84530 Mouse Controller is specially designed to control serial mouse or PS/2 mouse device. This single chip can interface three key-switches and 4 X-Y photo-couples directly to RS-232C or 8042 controller.

### **FEATURES**

- Include PnP software scrolling function
- Using  $50k\Omega \pm 1\%$  resistor for RC oscillation.
- Compatible with legacy PS/2 mouse.
- Compatible with Microsoft serial mouse.
- Compatible with Microsoft PS/2 mouse.
- Serial or PS/2 port auto-detect.
- 100 bytes PnP ID code could be filled by code layer.
- Built-in noise immunity circuit.
- The sampiling rate of motion detector is up to 65KHz.
- Built-in three zener diodes : one in VDD to VSS, two in RTS to VDD.
- CMOS push-pull RXD output.
- Built-in current comparator for photo-couples input.
- Built-in three step dynamic input impedance.
- Three key-switches and four photo-couples inputs.
- RTS debouncing circuit included.
- Photo couple test mode included.
- Low power dissipation.

### APPLICATION

- Serial PnP mouse.
- PS/2 mouse.
- Combo mouse.

### **PIN ASSIGNMENT**





### FUNCTIONAL BLOCK DIAGRAM



### **PIN DESCRIPTIONS**

| Symbol   | I/O | Function  |
|----------|-----|---|
| OPT      | I/O | INPUT: $200k\Omega$ pull low to VSS.  |
|          |     | When OPT is connected to VDD, EM84530 will enter test mode. In test mode,         |
|          |     | L will be the output of X1, while M will be the output of X2. Toggling R key can  |
|          |     | change these output to be Y1,Y2 respectively.                                     |
| OSC.OUT  | 0   | The RC oscillation clock output. Or 3mA sink current output for X, Y photo        |
|          |     | emitters.   |
| OSCR     | I   | Connect 50k $\Omega$ ±1% precise resistor for oscillation.                        |
| CLK/RTS  | I/O | Connect directly to 8042 auxiliary port CLK line in PS/2 mode or connect directly |
|          |     | to RS-232C RTS pin in serial mode. Auto-detect the operating port by this pin.    |
| DATA/RXD | I/O | Connect directly to 8042 auxiliary port DATA line in PS/2 mode or connect         |
|          |     | directly to RS-232C RXD pin in serial mode.                                       |
| R        | I   | Three key-switches inputs. $200k\Omega$ resistor pull low.                        |
| М        | I/O |   |
| L        | I/O |   |
| X1       | I   | Three step dynamic input impedance. If OSC.OUT is not connected to LEDs, the      |
| X2       | I   | dynamic input impedance will be off.  |
| Y1       | I   | Use current comparator to measure photo-couples "ON", or "OFF".                   |
| Y2       | I   |   |
| VSS      |     | Negative power.   |
| VDD      |     | Power line.   |



### **FUNCTION DESCRIPTIONS**

#### (I) Serial Mouse :

In Microsoft mode, the transmission cycle consists of four bytes in one report. Each byte contains one start bit, 7 data bits and two stop bits. The first byte contains "L", "R" key status and four bits of the two most significant bits in horizontal counter and vertical counter. The second byte represents the value accumulated by horizontal counter, the third byte is the data of the vertical counter. The last byte contains only "M" key status. The vertical data is transmitted in 2's complement.

Output byte arrange

| Bit no.  | <br>6 | 5   | 4   | 3   | 2   | 1   | 0   |
|----------|-------|-----|-----|-----|-----|-----|-----|
| 1st byte | <br>1 | L   | R   | V7' | V6' | H7  | H6  |
| 2nd byte | <br>0 | H5  | H4  | H3  | H2  | H1  | HO  |
| 3rd byte | <br>0 | V5' | V4' | V3' | V2' | V1' | V0' |
| 4th byte | <br>0 | 0   | Μ   | 0   | 0   | 0   | 0   |

Plug & Play ID code

When RTS input from low to high, EM83810 will send a string ID code. Customer can specify the contains of the code area and the total lenth below 100 bytes by changing the code layer.

| Field Name    | Length | Field Data                      | Description       |
|---------------|--------|---------------------------------|-------------------|
| Other ID      | <17    | 4D, 5A, 40, 00, 00, 00          | ID for legacy     |
| Begin ID      | 1      | 08                              | Begin PnP ID      |
| PnP Revision  | 2      | 01, 24                          | Version 1.00      |
| EISA ID       | 3      | 25, 2D, 23                      | EMC               |
| Product ID    | 4      | 10, 10, 10, 11                  | 0001              |
| Serial Number | 9      | 3C                              | None provided     |
| Class ID      | <34    | 3C, 2D, 2F, 35, 33, 25          | Mouse Class       |
| Driver ID     | <42    | 3C, 30, 2E, 30, 10 26, 10, 21   | PnP0F0A           |
| User Name     | <42    | 3C, 25, 2D, 23, 00, 33, 23, 32, | EMC SCROLLING     |
|               |        | 2F, 2C, 2C, 29, 2E, 27, 00, 33, | SERIAL MOUSE      |
|               |        | 25, 32, 29, 21, 2C, 00, 2D, 2F, |                   |
|               |        | 35, 33, 25                      |                   |
| Checks um     | 2      | 21, 15                          | 2 bytes checks um |
| End PnP       | 1      | 09                              | End PnP ID        |

(II) Legacy PS/2 mouse operating:

(A) Operating mode

There are four operating modes in PS/2 mouse:

a. Reset Mode:

In this mode a self-test is initiated during power-on or by a Reset command. After reset signal, PS/2 mouse will

- (a) Send completion code AA & ID code 00.
- (b) Set default :



sampling rate: 100 reports/s non-autospeed stream mode 2 dot/count disable

### b. Stream Mode:

The maximum rate of transfer is the programmed sample rate. Data report is transmitted if (a) switch is pressed (b) movement has been detect

c. Remote Mode:

Data is transmitted only in response to a Read Data command.

d. Wrap Mode:

Any byte of data sent by the system, except hex EC (Reset wrap mode) or hex FF (Reset), is returned by EM84530.

- B). PS/2 Mouse Data Report:
  - a). In stream mode: A data report is sent at the end of a sample interval.
  - b). In remote mode: A data report is sent in response to Read Data command.
  - c). Data report format:

| Byte | Bit | Description                            |  |
|------|-----|--|--|
| 1    | 0   | Left button status; $1 = pressed$      |  |
|      | 1   | Right button status; $1 = pressed$     |  |
|      | 2   | Middle button status; $1 = pressed$    |  |
|      | 3   | Reserve                                |  |
|      | 4   | X data sign; $1 = negative$            |  |
|      | 5   | Y data sign; $1 = negative$            |  |
|      | 6   | X data overflow; $1 = \text{overflow}$ |  |
|      | 7   | Y data overflow; 1 = overflow          |  |
| 2    | 0-7 | X data ( D0 - D7 )                     |  |
| 3    | 0-7 | Y data ( D0 - D7 )                     |  |

- C) PS/2 mouse Data Transmission:
  - a). EM84530 generates the clocking signal when sending data to and receiving data from the system.
  - b). The system requests EM84530 receive system data output by forcing the DATA line to an inactive level and allowing CLK line to go to an active level.





c). Data transmission frame:

| Bit | Function                |
|-----|-------------------------|
| 1   | Start bit ( always 0 )  |
| 2-9 | Data bits (D0 - D7)     |
| 10  | Parity bit (odd parity) |
| 11  | Stop bit ( always 1 )   |

d). Data Output ( data from EM84530 to system ):

If CLK is low ( inhibit status ), data is no transmission.

If CLK is high and DATA is low (request-to-send), data is updated. Data is received from the system and no transmission are started by EM84530 until CLK and DATA both high. If CLK and DATA both are high, the transmission is ready. DATA is valid prior to the falling edge of CLK and beyond the rising edge of CLK. During transmission, EM84530 check for line contention by checking for an inactive level on CLK at intervals not to exceed 100u sec. Contention occurs when the system lowers CLK to inhibit EM84530 output after EM84530 has started a transmission. If this occurs before the rising edge of the tenth clock, EM84530 internal store its data in its buffer and returns DATA and CLK to an active level. If the contention does not occur by the tenth clock, the transmission is complete.

Following a transmission, the system inhibits EM84530 by holding CLK low until it can service the input or until the system receives a request to send a response from EM84530.

e). Data Input ( from system to EM84530 ):

The system first check if EM84530 is transmitting data. If EM84530 is transmitting, the system can override the output forcing CLK to an inactive level prior to the tenth clock. If EM84530 transmission is beyond the tenth clock, the system receives the data. If EM84530 is not transmitting or if the system choose to override the output, the system force CLK to an inactive level for a period of not less than 100µ sec while preparing for output. When the system is ready to output start bit (0), it allows CLK go to active level. If request-to-send is detected, EM84530 clocks 11 bits. Following the tenth clock EM84530 checks for an active level on the DATA line, and if found, force DATA low, and clock once more. If occurs framing error, EM84530 continue to clock until DATA is high, then clocks the line control bit and request a Resend. When the system sends out a command or data transmission that requires a response, the system waits for EM84530 to response before sending its next output.

D). PS/2 Mouse Error Handling:

- a). A Resend command (FE) following receipt of an invalid input or any input with incorrect parity.
- b). If two invalid input are received in succession, an error code of hex (FC) is send to the system.
- c). The counter accumulators are cleared after receiving any command except "Resend".
- d). EM84530 receives a Resend command (FE), it transmit its last packet of data.
- e). In the stream mode "Resend" is received by EM84530 following a 3-byte data packet transmission to the system. EM84530 resend the 3-byte data packet prior to clearing the counter.



Preliminary

- f). A response is sent within 25 ms if
  - a). The system requires a response
- b). An error is detected in the transmission
- g). If EM84530 is in the stream mode :
  - a). The system disables EM84530 before issuing any command requiring a response.
- b). When a command requiring a response is issued by the system ,another command should not be issue until either the response is received or 25ms has passed.
- E). PS/2 Mouse Commands Description:

There are 16 valid commands that transmits between the system and EM84530. The "FA" code is always the first response to any valid input received from the system other than a Set Wrap Mode or Resend command. The following table list the commands:

| Hex Code | Command           | Echo code   |
|----------|-------------------|-------------|
| FF       | Reset             | FA,AA,00    |
| FE       | Resend            | XX,(XX,XX)  |
| F6       | Set Default       | FA          |
| F5       | Disable           | FA          |
| F4       | Enable            | FA          |
| F3,XX    | Set Sampling Rate | FA,FA       |
| F2       | Read Device Type  | FA,00       |
| F0       | Set Remote Mode   | FA          |
| EE       | Set Wrap Mode     | FA          |
| EC       | Reset Wrap Mode   | FA          |
| EB       | Read Data         | FA,XX,XX,XX |
| EA       | Set Stream Mode   | FA          |
| E9       | Status Request    | FA,XX,XX,XX |
| E8,XX    | Set Resolution    | FA,FA       |
| E7       | Set Auto-speed    | FA          |
| E6       | Reset Auto-speed  | FA          |

The following describes valid commands:

#### a). Reset (FF)

EM84530 operation:

- a). Completion the reset.
- b). Transmitted FA, AA, 00 to the system.
- c). Set default:

sampling rate: 100 reports/s non-autospeed stream mode 2 dots/count disable



- b). Resend (FE)
  - a). Any time EM84530 receives an invalid command, it returns a Resend command to the system.
  - b). When EM84530 receives a Resend command, it retransmits its last packet of data. If the last packet was a Resend command, it transmits the packet just prior to the Resend command.
  - c). In stream mode, if a Resend command is received by EM84530 immediately following a 3-byte data packet transmission to the system.
- c). Set Default (F6)

The command reinitializes all conditions to the power-on defaults.

d). Disable (F5)

This command is used in the stream mode to stop transmissions from EM84530.

e). Enable (F4)

Begins transmissions, if in stream mode.

f). Set Sampling Rate (F3,XX)

In the stream mode, this command sets the sampling rate to the value indicated by byte hex XX, shown in following:

| Second byte XX | Sample Rate |
|----------------|-------------|
| 0A             | 10/sec      |
| 14             | 20/sec      |
| 28             | 40/sec      |
| 3C             | 60/sec      |
| 50             | 80/sec      |
| 64             | 100/sec     |
| C8             | 200/sec     |

- g). Read Device Type (F2) EM84530 always echoes "FA,00 " following this command.
- h). Set Remote Mode (F0) Data value are reported only in response to a Read Data command.
- i). Set Wrap Mode ( EE ) Wrap mode remains until Reset ( FF ) or Reset Wrap Mode ( EC ) is received.
- j). Reset Wrap Mode (EC) EM84530 returns to the previous mode of operation after receiving this command.
- k). Read Data ( EB )

This command is executed in either remote or stream mode. The data is transmitted even if there has been no movement since the last report or the button status is unchanged. Following a Read Data command, the registers are cleared after a data transmission.

l). Set Stream Mode ( EA )

This command sets EM84530 in stream mode.





### m). Status Request ( E9 )

When this command is issued by the system, EM84530 respond with a 3-byte status report as follows:

| Byte | Bit | Description                            |
|------|-----|--|
| 1    | 0   | 1 = Right button pressed               |
|      | 1   | 1 = Middle button pressed              |
|      | 2   | 1 = Left button pressed                |
|      | 3   | Reserved                               |
|      | 4   | 0 = Normal speed, 1 = Autospeed        |
|      | 5   | 0 = Disabled, $1 = $ Enabled           |
|      | 6   | 0 = Stream mode, $1 =$ Remote mode     |
|      | 7   | Reserved                               |
| 2    | 0-7 | Current resolution setting ( D0 - D7 ) |
| 3    | 0-7 | Current sampling rate ( D0 - D7 )      |

### n). Set Resolution ( E8,XX )

EM84530 provides four resolutions selected by the second byte of this command as follows:

| Second Byte XX | Resolution   |
|----------------|--------------|
| 00             | 8 dots/count |
| 01             | 4 dots/count |
| 02             | 2 dots/count |
| 03             | 1 dots/count |

#### o). Set Autospeed ( E7 )

At the end of a sample interval in the stream mode, the current X and Y data values are converted new values. The sign bits are not involved in this conversion. The conversion is only in stream mode. The relationship between the input and output count follows:

| Input  | Ouput |
|--------|-------|
| 0      | 0     |
| 1      | 1     |
| 2      | 1     |
| 3      | 3     |
| 4      | 6     |
| 5      | 9     |
| N(≥6 ) | 2.0*N |

p). Reset Autospeed ( E6 )

This command restore normal speed.



- (III) Microsoft PS/2 scrolling mouse mode:
  - (A) Entering procedure: Except in WRAP mode, while EM84530 received the following consecutive command.
    - i. F3 C8 ---- set sampling rate 200/sec
    - ii. F3 64 ---- set sampling rate 100/sec
    - iii. F3 50 ---- set sampling rate 80/sec
  - (B) Operating:
    - a. All of the commands in legacy mode still be valid.
    - b. The ID code of read device type command (F2) will changed from "00" to be "03".
    - c. Data report will be four bytes format:

| Byte | Bit | Description                            |
|------|-----|--|
| 1    | 0   | Left button status; $1 = pressed$      |
|      | 1   | Right button status; $1 = pressed$     |
|      | 2   | Middle button status; 1 = pressed      |
|      | 3   | Reserve                                |
|      | 4   | X data sign; $1 = negative$            |
|      | 5   | Y data sign; $1 = negative$            |
|      | 6   | X data overflow; $1 = \text{overflow}$ |
|      | 7   | Y data overflow; $1 = \text{overflow}$ |
| 2    | 0-7 | X data ( D0 - D7 )                     |
| 3    | 0-7 | Y data ( D0 - D7 )                     |
| 4    | 0-7 | Reserved (0)                           |

(C) Exiting Microsoft PS/2 mouse mode:

There are two ways to exit:

- a. Power off.
- b. Reset command (FF).



### ABSOLUTE MAXIMUM RATINGS

| Parameter                 | R    | Unit |    |
|---------------------------|------|------|----|
|                           | Min. | Max. |    |
| Temperature under bias    | 0    | 70   | °C |
| Storage temperature range | -65  | 150  | °C |
| Supply voltage            | -0.3 | 7.5  | V  |
| Power dissipation         | -    | 500  | mW |

### **DC ELECTRICAL CHARACTERISTICS** ( $T_A = 25^{\circ}C$ to $70^{\circ}C$ )

| Parameters                               | Sym.                | Min. | Typ. | Max. | Unit |
|--|---------------------|------|------|------|------|
| X1,X2,Y1,Y2 low input reference current  | I <sub>PL</sub>     | 70   | -    | -    | μΑ   |
| X1,X2,Y1,Y2 high input reference current | IPh                 | -    | -    | 106  | μA   |
| X1,X2,Y1,Y2 input current (80µA          | A) V <sub>PI1</sub> | 0.8  | -    | 1.2  | V    |
| X1,X2,Y1,Y2 input current (500µA         | A) V <sub>PI2</sub> | 1.5  | -    | 2.1  | V    |
| L,M,R,OPT input low voltage              | Vail                | -    | -    | 1.5  | V    |
| L,M,R,OPT input high voltage             | Vaih                | 3.5  | -    | -    | V    |
| L,M,R input current (Vin=5)              | V) Rmi              | 18   | -    | 56   | μΑ   |
| OPT input current                        | Ixi                 | -18  | -    | -56  | μΑ   |
| OPT high output current (Iopt=20m/       | A) Vopt             | 4.5  | -    | -    | V    |
| L,M,R,X1,X2,Y1,Y2 input leakage current  | Iil                 | 0    | -    | -1.0 | μA   |
| (Vin=0)                                  | V)                  |      |      |      |      |
| OPT input leakage current (Vin=5)        | V) Iih              | 0    | -    | 1.0  | μA   |
| OSC.OUT                                  | Iosc                | 3    | -    | 3.6  | mA   |
| Sink current                             |                     |      |      |      |      |

### **PS/2 mouse mode :** ( $T_A = 25^{\circ}C$ to $70^{\circ}C$ )

| Parameters                       |             | Sym.            | Min. | Тур. | Max. | Unit |
|----------------------------------|-------------|-----------------|------|------|------|------|
| Operating voltage                |             | VDD             | 4.5  | -    | 5.5  | V    |
| Operating current                | (no load)   | I <sub>Op</sub> | -    | -    | 1    | mA   |
| CLK, DATA                        |             | Vt+             | 3.2  | -    | 3.8  | V    |
| postive-going threshold voltage  |             |                 |      |      |      |      |
| CLK, DATA                        |             | Vt -            | 1.2  | -    | 1.9  | V    |
| negative-going threshold voltage |             |                 |      |      |      |      |
| DATA, CLK input current          | (Vin=0V)    | Idc             | 0.56 | -    | 1.86 | mA   |
| DATA,CLK low output voltage      | (Iprl=-2mA) | Vprl            | -    | -    | 0.4  | V    |
|                                  |             |                 |      |      |      |      |

Serial mouse mode :  $(T_A = 25^{\circ}C \text{ to } 70^{\circ}C)$ 

| Parameters  | Sym.  | Min. | Тур. | Max. | Unit |
|---|-------|------|------|------|------|
| Operating voltage                                     | VDD   | 4    | 5.6  | 6.2  | V    |
|   | VRTS  | -    | 12.2 | 13   | V    |
| Operating current (VDD=5.4V, RTS=VDD)                 | IOP1  | -    | -    | 1    | mA   |
| Operating current (VDD=6.2V, RTS=VDD)                 | IOP2  | 3    | -    | -    | mA   |
| RTS operating current (VDD=5.6V, RTS=11V)             | Irts1 | -    | -    | 1.8  | mA   |
| RTS operating current (VDD=5.4V, RTS=12.5V)           | Irts2 | 4    | -    | -    | mA   |
| RXD high output voltage(Vrh=Vrts-2.6V)                | Irh   | 2    | -    | -    | mA   |
| RXD low output voltage (Vrl=Vss+2.6V)                 | Irl   | -    | -    | -2   | mA   |
| RTS high input voltage                                | Vrts+ | 9.6  | -    | -    | V    |
| RTS low input voltage                                 | Vrts- | -    | -    | 6.8  | V    |
| * All parameters in above table are compared with VSS |       |      |      |      |      |



# **Preliminary** AC ELECTRICAL CHARACTERISTICS (T<sub>A</sub>=25°C to 70°C) PS/2 mouse mode ·

### **PS/2** mouse mode :

| Parameters  | Sym. | Min.    | Тур. | Max.    | Unit |
|---|------|---------|------|---------|------|
| Oscillating Frequency   | Fosc | 37.0-3% | 37.0 | 37.0+3% | KHz  |
| Key Debounce  | Tkd  | -       | 12   | -       | ms   |
| Rising Edge Crossed Width   | Tr   | 13.5    | -    | -       | us   |
| Falling Edge Crossed Width  | Tf   | 13.5    | -    | -       | us   |
| Mouse CLK Active Time   | Tmca | -       | 40.5 | -       | us   |
| Mouse CLK Inactive Time   | Tmci | -       | 40.5 | -       | us   |
| Time that Mouse Sample DATA from  | Tmdc | -       | 13.5 | -       | us   |
| CLK rising Edge   |      |         |      |         |      |
| System CLK Active Time  | Tsca | -       | 40.5 | -       | us   |
| System CLK Inactive Time  | Tsci | -       | 40.5 | -       | us   |
| Time from DATA Transition to Falling Edge of CLK  | Tsdc | -       | 13.5 | -       | us   |
| Time from rising Edge of CLK to DATA Transition   | Tscd | -       | 27.0 | -       | us   |
| Time to mouse Inhibit after the 11th CLK to<br>ensure mouse does not start another Transmission | Tpi  | 0       | -    | 50      | us   |

#### Serial mouse mode :

| Parameters                 | Sym. | Min.    | Тур.  | Max.    | Unit |
|----------------------------|------|---------|-------|---------|------|
| Oscillating Frequency      | Fosc | 32.4-3% | 32.4  | 32.4+3% | KHz  |
| Key Debounce               | Tkd  | -       | 13    | -       | ms   |
| Rising Edge Crossed Width  | Tr   | 15.4    | -     | -       | us   |
| Falling Edge Crossed Width | Tf   | 15.4    | -     | -       | us   |
| Transmission Time          | Tmx  | -       | 33.33 | -       | ms   |
| Start bit Time             | Ts   | -       | 833.3 | -       | us   |
| Data bit time              | Td   | -       | 833.3 | -       | us   |
| Stop bit Time              | Тр   | -       | 833.3 | -       | us   |
| Mode code delay Time       | Trd  | 11      | -     | 14      | ms   |

X1, X2, Y1, Y2 Input Impedance





### TIMING DIAGRAM

### (A) PS/2 mouse mode

(A) Photo-couples pulse width



### (B) Receiving Data



### (C) Sending Data





### (B) Serial mouse mode :

(A) RXD output :

| Key in/release | 7    |
|----------------|------|
| Mouse RXD      | <br> |

(B) Bytes structure :



(C) Bits structure :



(D) PnP ID code echo timing :





Preliminary

### **APPLICATION CIRCUIT**

